

CS 240 – Data Structures and Data Management

Module 6: Dictionaries for special keys

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Based on lecture notes by many previous cs240 instructors

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Winter 2021

Outline

- 1 Lower bound
- 2 Interpolation Search
- 3 Tries
 - Standard Tries
 - Variations of Tries
 - Compressed Tries

Lower bound for search

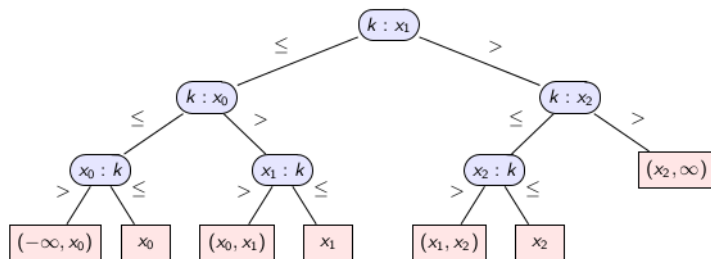
The fastest realizations of *ADT Dictionary* require $\Theta(\log n)$ time to search among n items. Is this the best possible?

Lower bound for search

The fastest realizations of *ADT Dictionary* require $\Theta(\log n)$ time to search among n items. Is this the best possible?

Theorem: In the comparison model (on the keys), $\Omega(\log n)$ comparisons are required to search a size- n dictionary.

Proof: via decision tree



But can we beat the lower bound for special keys?



Remark: could also use



Claim: an algorithm (in the comparison model) to do search
in a size- n dictionary \Rightarrow a decision tree
with at least $n+1$ leaves.

$x_0 < x_1$

```
if k ≤ x0
  if x0 ≤ k
    return "found", 0
  else
    return "not found"
else
  if k ≤ x1
    if x1 ≤ k
      return "found", 1
    else
      return "not found"
  else
    return "not found"
```

$k \leq x_0$

$k < x_0$

$k > x_0$

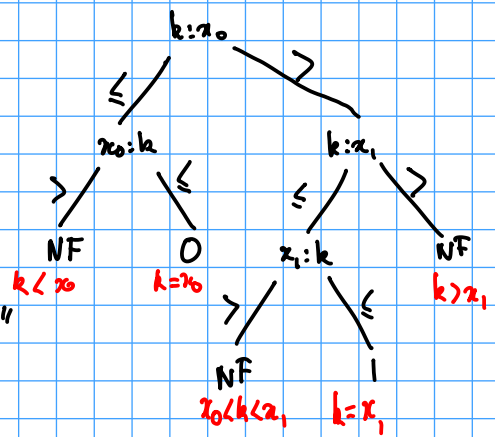
$x_0 < k \leq x_1$

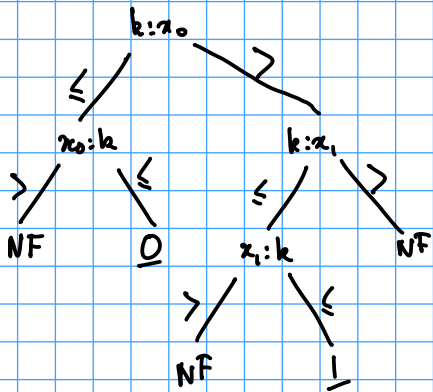
$x_0 < k < x_1$

$k > x_1$

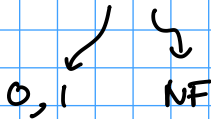
$x_0 < x_1$

```
if k ≤ x₀
  if x₀ ≤ k
    return "found", 0
  else
    return "not found"
else
  if k ≤ x₁
    if x₁ ≤ k
      return "found", 1
    else
      return "not found"
  else
    return "not found"
```





at least $3 = 2 + 1$ leaves



Let h be the worst-case # of comparisons that we do (for n keys)

→ any possible input k reaches a leaf after doing at most h comparisons

→ in the decision tree, there are at least $n+1$ leaves of depth $\leq h$.

In any binary tree, the number of leaves of depth $\leq h$ is at most 2^h . Proof: induction on h .

$$n+1 \leq \# \text{ of leaves of } \leq 2^h$$
$$\text{depth} \leq h$$

$$\rightarrow n+1 \leq 2^h$$

$$\rightarrow \log(n+1) \leq h.$$

Binary Search

Recall the run-times in a *sorted array*:

- *insert, delete*: $\Theta(n)$
- *search*: $\Theta(\log n)$

binary-search(A, n, k)

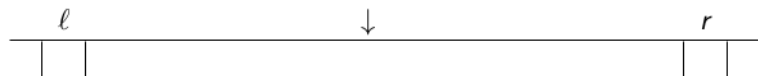
A: Sorted array of size n , k : key

1. $\ell \leftarrow 0, r \leftarrow n - 1$
2. **while** ($\ell \leq r$)
3. $m \leftarrow \lfloor \frac{\ell+r}{2} \rfloor$
4. **if** ($A[m] < k$) **then** $\ell = m + 1$
5. **else if** ($k < A[m]$) **then** $r = m - 1$
6. **else return** "found at $A[m]$ "
7. **return** "not found, but would be between $A[\ell-1]$ and $A[\ell]$ "

$r = \ell + 1$

Interpolation Search: Motivation

binary-search($A[\ell, r], k$): Compare at index $\lfloor \frac{\ell+r}{2} \rfloor = \ell + \lfloor \frac{1}{2}(r - \ell) \rfloor$



Interpolation Search: Motivation

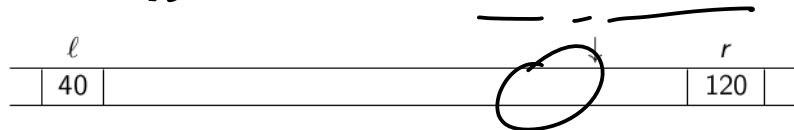
binary-search($A[\ell, r], k$): Compare at index $\lfloor \frac{\ell+r}{2} \rfloor = \ell + \lfloor \frac{1}{2}(r - \ell) \rfloor$



Question: If keys are *numbers*, where would you expect key $k = 100$?

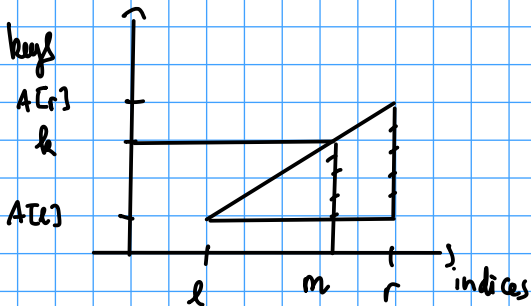
Interpolation Search: Motivation

binary-search($A[\ell, r], k$): Compare at index $\lfloor \frac{\ell+r}{2} \rfloor = \ell + \lfloor \frac{1}{2}(r - \ell) \rfloor$



Question: If keys are *numbers*, where would you expect key $k = 100$?

interpolation-search($A[\ell, r], k$): Compare at index $\ell + \underbrace{\left\lfloor \frac{k - A[\ell]}{A[r] - A[\ell]} (r - \ell) \right\rfloor}_{m}$ //



$$\frac{A[r] - A[l]}{r - l} = \frac{k - A[l]}{m - l}$$

$$\frac{m - l}{r - l} = \frac{k - A[l]}{A[r] - A[l]} \leadsto m = l + \frac{k - A[l]}{A[r] - A[l]} (r - l).$$

Interpolation Search Example

0	1	2	3	4	5	6	7	8	9	10
0	1	2	3	449	450	600	800	1000	1200	1500

interpolation-search(A[0..10],449):

Interpolation Search Example

0	1	2	3	4	5	6	7	8	9	10
0	1	2	3	449	450	600	800	1000	1200	1500
ℓ		\uparrow								r

interpolation-search(A[0..10],449):

- Initially $\ell = 0$, $r = n - 1 = 10$, $m = \ell + \lfloor \frac{449-0}{1500-0}(10-0) \rfloor = \ell + 2 = 2$

Interpolation Search Example

0	1	2	3	4	5	6	7	8	9	10
0	1	2	3	449	450	600	800	1000	1200	1500
			ℓ		\uparrow					r

interpolation-search(A[0..10],449):

- Initially $\ell = 0$, $r = n - 1 = 10$, $m = \ell + \lfloor \frac{449-0}{1500-0}(10-0) \rfloor = \ell + 2 = 2$
- $\ell = 3$, $r = 10$, $m = \ell + \lfloor \frac{449-3}{1500-3}(10-3) \rfloor = \ell + 2 = 5$

Interpolation Search Example

0	1	2	3	4	5	6	7	8	9	10
0	1	2	3	449	450	600	800	1000	1200	1500

ℓ \uparrow, r

interpolation-search(A[0..10],449):

- Initially $\ell = 0$, $r = n - 1 = 10$, $m = \ell + \lfloor \frac{449-0}{1500-0}(10-0) \rfloor = \ell + 2 = 2$
- $\ell = 3$, $r = 10$, $m = \ell + \lfloor \frac{449-3}{1500-3}(10-3) \rfloor = \ell + 2 = 5$
- $\ell = 3$, $r = 4$, $m = \ell + \lfloor \frac{449-3}{449-3}(4-3) \rfloor = \ell + 1 = 4$, found at A[4]

Interpolation Search Example

0	1	2	3	4	5	6	7	8	9	10
0	1	2	3	449	450	600	800	1000	1200	1500

Handwritten annotations: A bracket above indices 0-3, another above 6-9. Below the array, arrows indicate pointer updates: \uparrow_l from 0 to 1, \uparrow_m from 2 to 3, \uparrow_l from 3 to 4, \uparrow_r from 10 to 4, \uparrow_m from 5 to 4, and \uparrow_r from 10 to 10.

interpolation-search(A[0..10], 449):

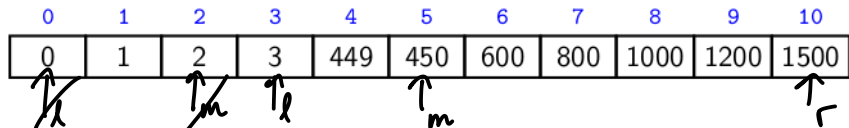
- Initially $l = 0$, $r = n - 1 = 10$, $m = l + \lfloor \frac{449-0}{1500-0}(10-0) \rfloor = l + 2 = 2$
- $l = 3$, $r = 10$, $m = l + \lfloor \frac{449-3}{1500-3}(10-3) \rfloor = l + 2 = 5$
- $\odot l = 3$, $r = 4$, $m = l + \lfloor \frac{449-3}{449-3}(4-3) \rfloor = l + 1 = 4$, found at $A[4]$

Works well if keys are *uniformly* distributed:

- Can show: Recurrence relation is $T^{(\text{avg})}(n) = T^{(\text{avg})}(\sqrt{n}) + \Theta(1)$ //
- This resolves to $T^{(\text{avg})}(n) \in \Theta(\log \log n)$. //

But: Worst case performance $\Theta(n)$ //

Interpolation Search Example



interpolation-search(A[0..10], ~~449~~):

- Initially $l = 0$, $r = n - 1 = 10$, $m = l + \lfloor \frac{449-0}{1500-0}(10-0) \rfloor = l + 2 = 2$
- $l = 3$, $r = 10$, $m = l + \lfloor \frac{449-3}{1500-3}(10-3) \rfloor = l + 2 = 5$
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Works well if keys are *uniformly* distributed:

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- This resolves to $T^{(\text{avg})}(n) \in \Theta(\log \log n)$.

But: Worst case performance $\Theta(n)$

$$T(n) = T(\sqrt{n}) + c$$

$$2 \rightarrow 2^2 \rightarrow 2^4 \rightarrow 2^8 \rightarrow 2^{16} \rightarrow \dots \rightarrow \underline{2^{2^i}} \rightarrow \dots$$

$$\rightarrow T(2^{2^i}) = T(2^{2^{i-1}}) + c$$

$$= T(2^{2^{i-2}}) + 2c$$

$$= T(2^{2^{i-3}}) + 3c$$

$$= \dots = T(2^{2^{i-i}}) + ic = T(2) + ic$$

$$\rightarrow \text{for } n = 2^{2^i}, T(n) = T(2) + c \cdot \log(\log(n)).$$

Interpolation Search

- Code very similar to binary search, but compare at interpolated index
- Need a few extra tests to avoid crash during computation of m .

interpolation-search(A, n, k)

A : Sorted array of size n , k : key

1. $\ell \leftarrow 0, r \leftarrow n - 1$
2. **while** ($\ell \leq r$)
3. **if** ($k < A[\ell]$ or $k > A[r]$) **return** “not found”
4. **if** ($A[\ell] = A[r]$) **then return** “found at $A[\ell]$ ”
5. $m \leftarrow \ell + \lfloor \frac{k - A[\ell]}{A[r] - A[\ell]} \cdot (r - \ell) \rfloor //$
6. **if** ($A[m] < k$) **then** $\ell = m + 1$
7. **else if** ($k < A[m]$) **then** $r = m - 1$
8. **else return** “found at $A[m]$ ”
9. // We always return from somewhere within while-loop

Outline

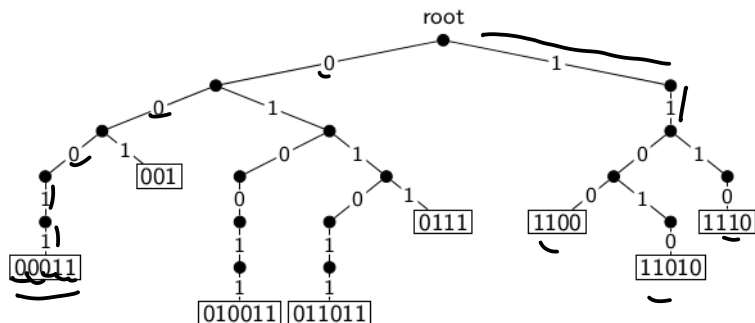
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 - Compressed Tries

Tries: Introduction

Trie (also known as **radix tree**): A dictionary for bitstrings.

(Should know: string, word, $|w|$, alphabet, prefix, suffix, comparing words,....)

- Comes from retrieval, but pronounced “try”
- A tree based on *bitwise comparisons*: Edge labelled with corresponding bit
- Similar to *radix sort*: use individual bits, not the whole key

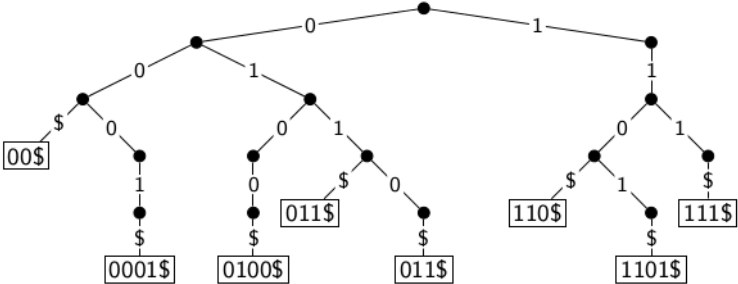


More on tries

Assumption: Dictionary is **prefix-free**: no string is a prefix of another

- Assumption satisfied if all strings have the same length.
- Assumption satisfied if all strings end with 'end-of-word' character \$.

Example: A trie for {00\$, 0001\$, 0100\$, 011\$, 0110\$, 110\$, 1101\$, 111\$}

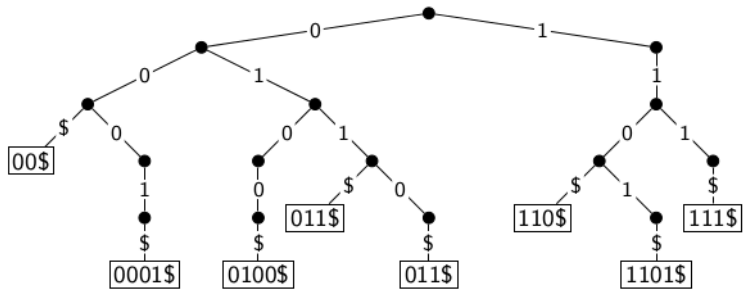


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Example: A trie for {00\$, 0001\$, 0100\$, 011\$, 0110\$, 110\$, 1101\$, 111\$}



Then items (keys) are stored *only* in the leaf nodes

Tries: Search

- start from the root and the most significant bit of x
- follow the link that corresponds to the current bit in x ;
return failure if the link is missing
- return success if we reach a leaf (it must store x)
- else recurse on the new node and the next bit of x

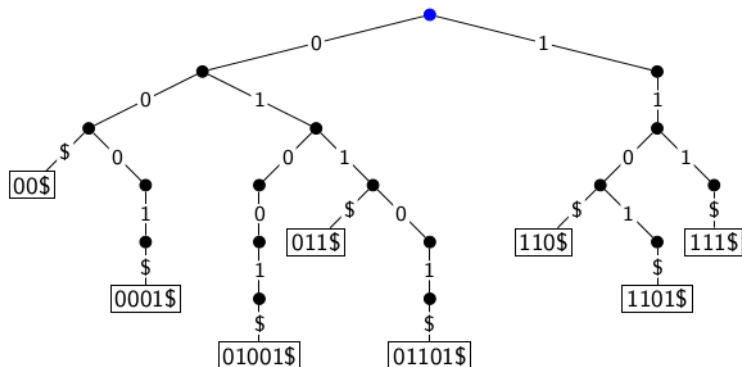
Trie::search($\underline{v} \leftarrow \text{root}, d \leftarrow 0, \underline{x}$)

v : node of trie; d : level of v , x : word stored as array of chars

1. **if** v is a leaf
2. **return** v
3. **else**
4. let v' be child of v labelled with $x[d]$
5. **if** there is no such child
6. **return** "not found"
7. **else** *Trie::search*($v', d + 1, x$)

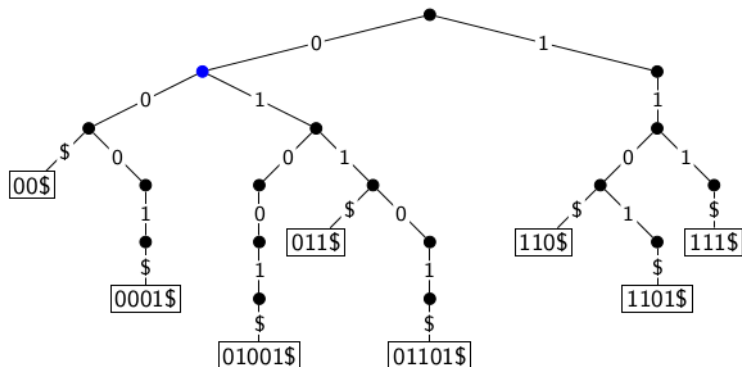
Tries: Search Example

Example: Trie::search(011\$)



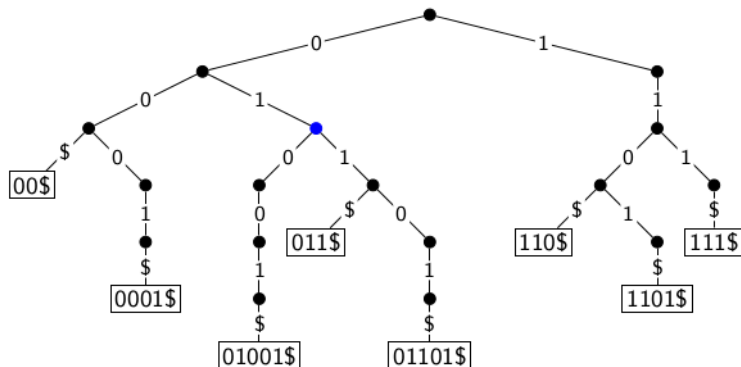
Tries: Search Example

Example: Trie::search(011\$)



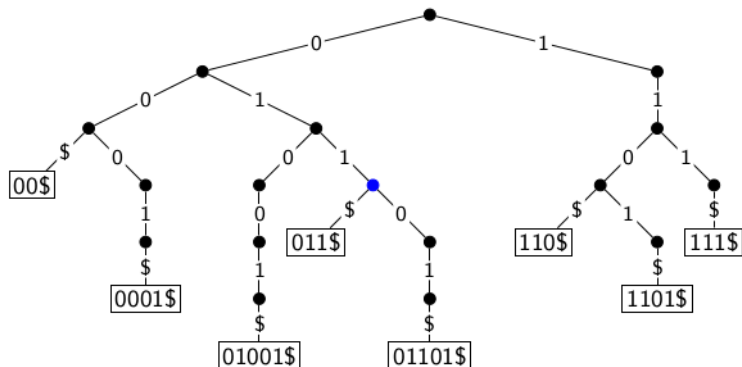
Tries: Search Example

Example: Trie::search(011\$)



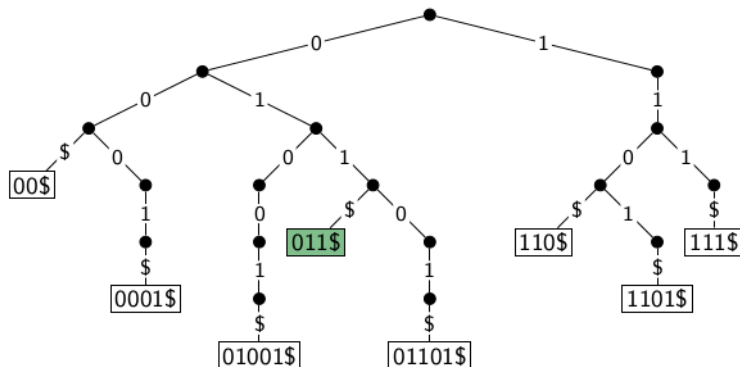
Tries: Search Example

Example: Trie::search(011\$)



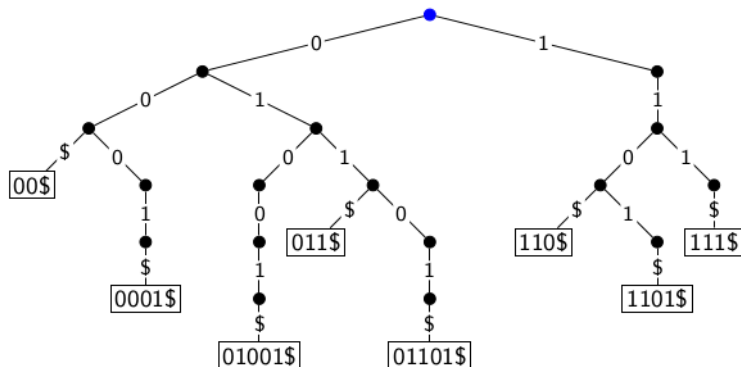
Tries: Search Example

Example: Trie::search(011\$) **successful**



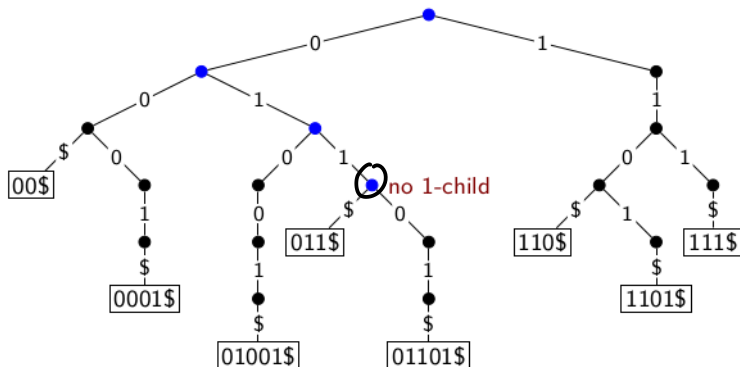
Tries: Search Example

Example: Trie::search(0111\$)



Tries: Search Example

Example: Trie::search(0111\$) **unsuccessful**

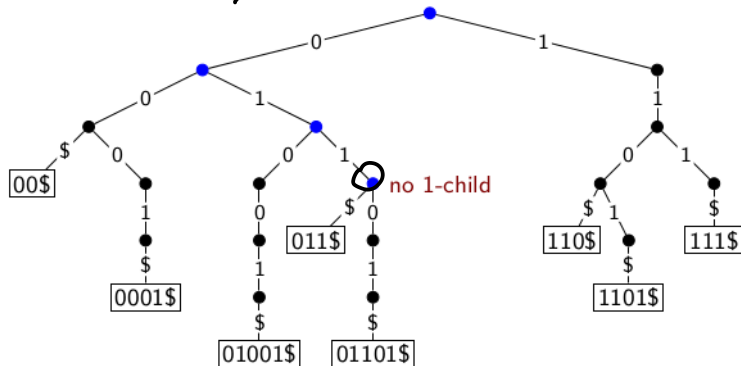


Tries: Insert & Delete

- *Trie::insert(x)*
 - ▶ Search for x , this should be unsuccessful
 - ▶ Suppose we finish at a node v that is missing a suitable child.
Note: x has extra bits left.
 - ▶ Expand the trie from the node v by adding necessary nodes that correspond to extra bits of x .
- *Trie::delete(x)*
 - ▶ Search for x
 - ▶ let v be the leaf where x is found
 - ▶ delete v and all ancestors of v until we reach an ancestor that has two children.
- **Time Complexity** of all operations: $\Theta(|x|)$
 $|x|$: length of binary string x , i.e., the number of bits in x

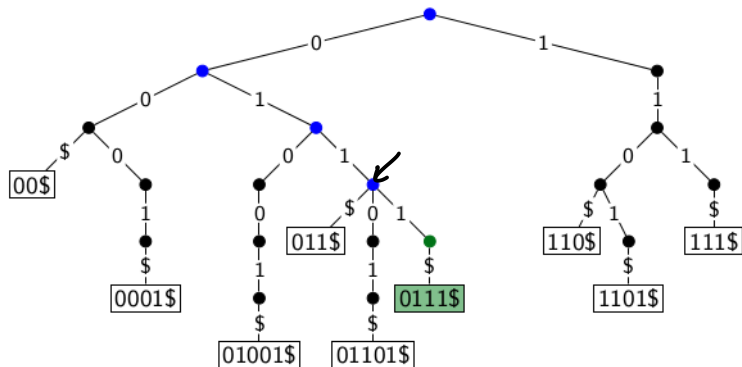
Tries: Insert Example

Example: *Trie::insert*(0111\$)



Tries: Insert Example

Example: *Trie::insert*(0111\$)



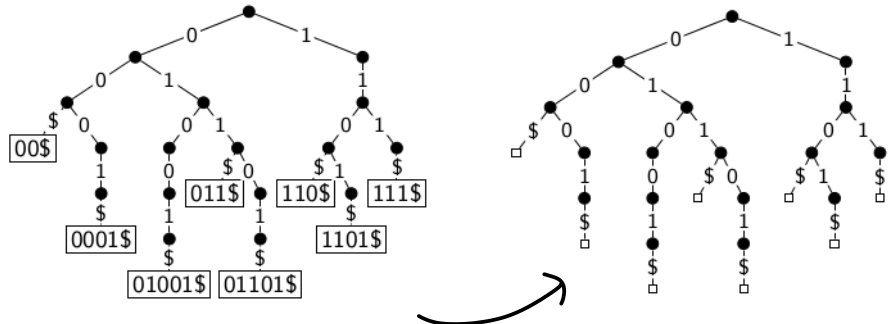
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 - Standard Tries
 - **Variations of Tries**
 - Compressed Tries

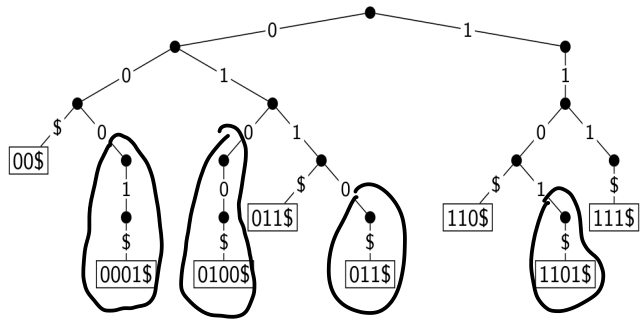
Variation 1 of Tries: No leaf labels

Do not store actual keys at the leaves.

- The key is stored implicitly through the characters along the path to the leaf. It therefore need not be stored again.



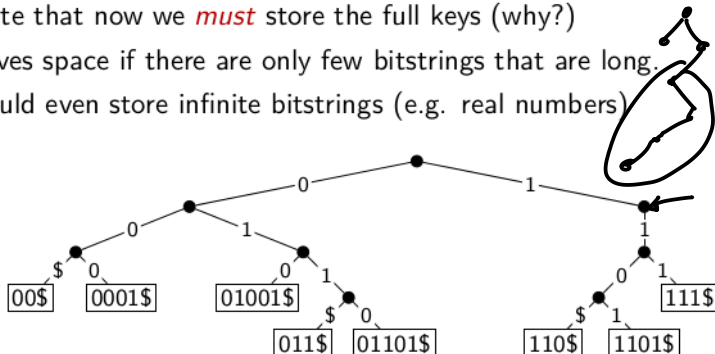
4



Variations 3 of Tries

Pruned Trie: Stop adding nodes to trie as soon as the key is unique.

- A node has a child only if it has at least two descendants.
- Note that now we *must* store the full keys (why?)
- Saves space if there are only few bitstrings that are long.
- Could even store infinite bitstrings (e.g. real numbers)



This is in practice the most efficient version of tries, but the operations get a bit more complicated.

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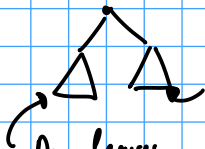
Proof: by induction on the height.

1) if $h = 0$



$n = 1$, no internal nodes \rightarrow OK.

2) suppose true for $0 \dots h-1$; prove it for a trie of height h .



n_1 leaves

at most $n_1 - 1$ internal nodes

n_2 leaves

at most $n_2 - 1$ internal nodes.

in the whole tree:

- # leaves = $n_1 + n_2$
- # internal nodes = # internal nodes on the left + # internal nodes on the right + 1

$$\leq n_1 - 1 + n_2 - 1 + 1 = \underbrace{n_1 + n_2 - 1}_{\text{\#leaves}}$$

Compressed Tries: Search

- start from the root and the bit indicated at that node
- follow the link that corresponds to the current bit in x ;
return failure if the link is missing
- if we reach a leaf, explicitly check whether word stored at leaf is x
- else recurse on the new node and the next bit of x

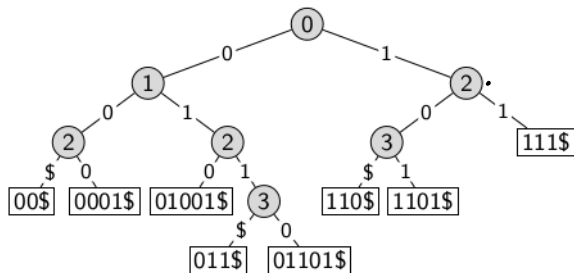
```
CompressedTrie::search( $v$   $\leftarrow$  root,  $x$ )
```

v : node of trie; x : word

1. **if** v is a leaf
2. **return** *strcmp*(x , v .key)
3. $d \leftarrow$ index stored at v
4. **if** x has at most d bits
5. **return** "not found"
6. $v' \leftarrow$ child of v labelled with $x[d]$
7. **if** there is no such child
8. **return** "not found"
9. *CompressedTrie::search*(v' , x)

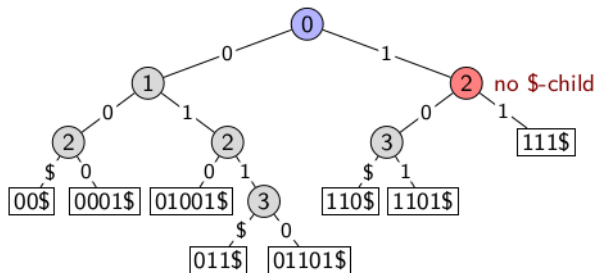
Compressed Tries: Search Example

Example: CompressedTrie::search(10\$)



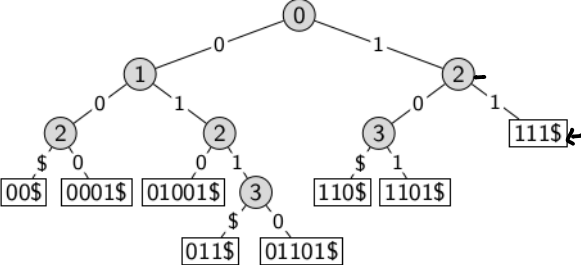
Compressed Tries: Search Example

Example: `CompressedTrie::search(10$)` **unsuccessful**



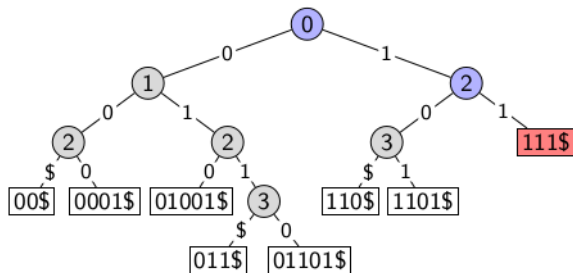
Compressed Tries: Search Example

Example: CompressedTrie::search(101\$)



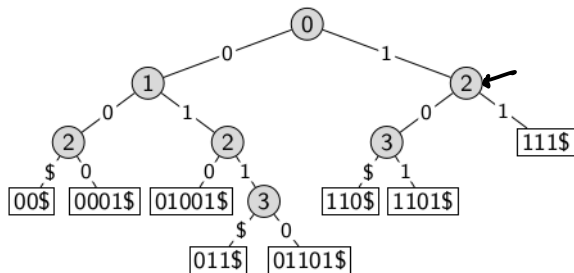
Compressed Tries: Search Example

Example: `CompressedTrie::search(101$)` **unsuccessful**



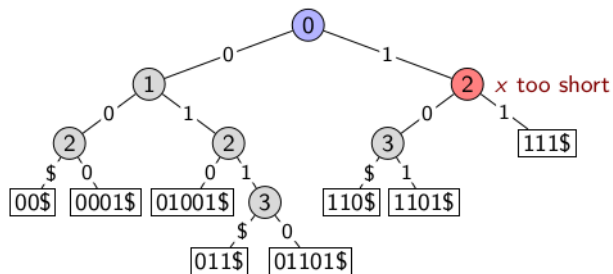
Compressed Tries: Search Example

Example: `CompressedTrie::search(1$)`



Compressed Tries: Search Example

Example: `CompressedTrie::search(1$)` **unsuccessful**



Compressed Tries: Insert & Delete

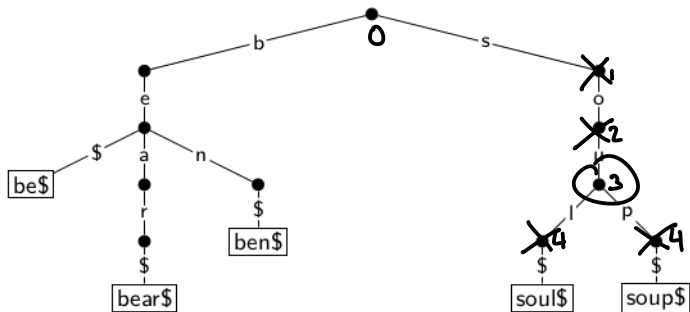
- *CompressedTrie::delete*(x):
 - ▶ Perform *search*(x)
 - ▶ Remove the node v that stored x
 - ▶ Compress along path to v whenever possible.
- *CompressedTrie::insert*(x):
 - ▶ Perform *search*(x)
 - ▶ Let v be the node where the search ended.
 - ▶ Conceptually simplest approach:
 - ★ Uncompress path from root to v .
 - ★ Insert x as in an uncompressed trie.
 - ★ Compress paths from root to v and from root to x .

But it can also be done by only adding those nodes that are needed, see the textbook for details.

- All operations take $O(|x|)$ time.

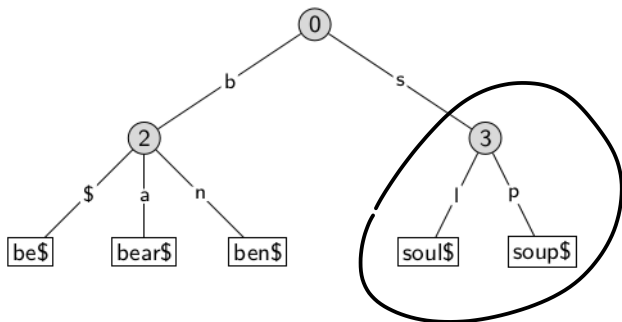
Multiway Tries: Larger Alphabet

- To represent *strings* over any *fixed alphabet* Σ
- Any node will have at most $|\Sigma| + 1$ children (one child for the end-of-word character \$)
- Example: A trie holding strings {bear\$, ben\$, be\$, soul\$, soup\$}



Compressed Multiway Tries

- **Variation:** Compressed multi-way tries: compress paths as before
- Example: A compressed trie holding strings {bear\$, ben\$, be\$, soul\$, soup\$}



Multiway Tries: Summary

- Operations *search*(x), *insert*(x) and *delete*(x) are exactly as for tries for bitstrings.
- Run-time $O(|x| \cdot (\text{time to find the appropriate child}))$

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Each node now has up to $|\Sigma| + 1$ children. How should they be stored?

Multiway Tries: Summary

- Operations *search*(x), *insert*(x) and *delete*(x) are exactly as for tries for bitstrings.
- Run-time $O(|x| \cdot (\text{time to find the appropriate child}))$

Each node now has up to $|\Sigma| + 1$ children. How should they be stored?

Solution 1: Array of size $|\Sigma| + 1$ for each node.

Complexity: $O(1)$ time to find child, $O(|\Sigma|)$ space per node.

Solution 2: List of children for each node.

Complexity: $O(|\Sigma|)$ time to find child, $O(\#\text{children})$ space.

Solution 3: Dictionary (AVL-tree?) of children for each node.

Complexity: $O(\log(\#\text{children}))$ time, $O(\#\text{children})$ space.

Best in theory, but not worth it in practice unless $|\Sigma|$ is huge.

In practice, use *hashing* (keys are in (typically small) range Σ).

Multiway Tries: Summary

- Operations *search*(x), *insert*(x) and *delete*(x) are exactly as for tries for bitstrings.
- Run-time $O(|x| \cdot (\text{time to find the appropriate child}))$

Each node now has up to $|\Sigma| + 1$ children. How should they be stored?

Solution 1: Array of size $|\Sigma| + 1$ for each node.

Complexity: $O(1)$ time to find child, $O(|\Sigma|)$ space per node.

Solution 2: List of children for each node.

Complexity: $O(|\Sigma|)$ time to find child, $O(\#\text{children})$ space.

Solution 3: Dictionary (AVL-tree?) of children for each node.

Complexity: $O(\log(\#\text{children}))$ time, $O(\#\text{children})$ space.

Best in theory, but not worth it in practice unless $|\Sigma|$ is huge.

In practice, use *hashing* (keys are in (typically small) range Σ).