

CS 341: ALGORITHMS

Lecture 11: graph algorithms II – finishing BFS, depth first search
Readings: see website

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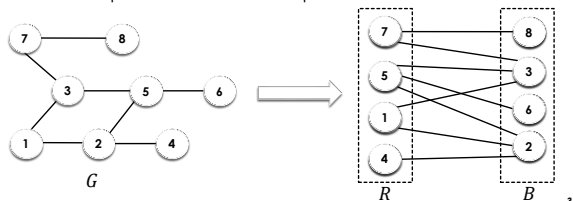
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BFS APPLICATION: TESTING WHETHER A GRAPH IS **BIPARTITE**

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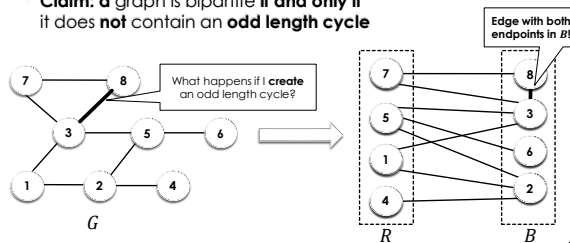
(UNDIRECTED) BIPARTITE GRAPHS AND BFS

- A graph is **bipartite** if the nodes can be **partitioned** into sets R and B such that **each edge** has one endpoint in R and one endpoint in B



CRUCIAL PROPERTY: NO ODD CYCLES

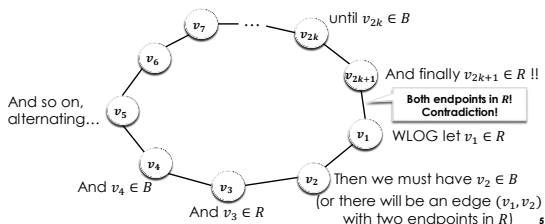
- Claim:** a graph is bipartite if and only if it does **not** contain an **odd length cycle**



PROOF

PART 1: ODD CYCLE \Rightarrow NOT BIPARTITE

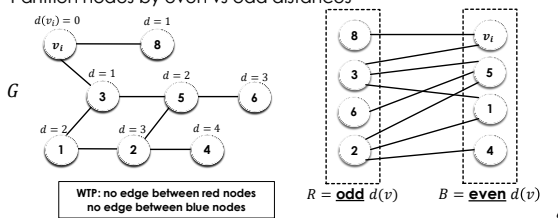
- Suppose there is an **odd** length cycle $v_1, v_2, \dots, v_{2k+1}, v_1$



PROOF

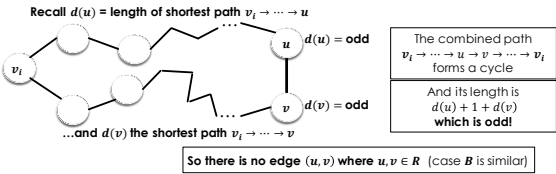
PART 2: ALL CYCLES HAVE EVEN LENGTH \Rightarrow BIPARTITE

- Let v_i be any node, and $d(v)$ be the distance from v_i to v
- Partition nodes by even vs odd distances



BAD EDGES MEAN ODD CYCLES

- Claim:** if there were an edge between red nodes, or between blue nodes, there would be an **odd length cycle**
- WLOG suppose for contradiction $(u, v) \in E$ where $u, v \in R$
- Since $u, v \in R$, distances $d(u)$ and $d(v)$ from v_i are **both odd**



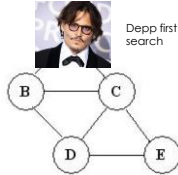
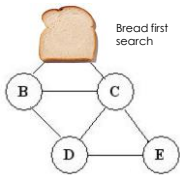
ALGORITHM FOR TESTING BIPARTITENESS

```

1 Bipartition(adj[1..n])
2   colour[1..n] = [white, ..., white]
3   dist[1..n] = [-infy, ..., infy]
4   for start = 1..n
5     if colour[start] is white
6       BFS(adj, start, colour, dist)
7
8   for edge in adj
9     let u and v be endpoints of edge
10    if (dist[u]%2) == (dist[v]%2) then
11      return NotBipartite
12
13  B = nodes u with even dist[u]
14  R = nodes u with odd dist[u]
15  return B, R
  
```

Annotations:

- Call BFS on each component to calculate distances for each node
- Modified BFS that reuses the same colour array and same dist array
- If both even or both odd
- Return an actual bipartition
- Runtime complexity? Can be done in $O(n+m)$



DEPTH FIRST SEARCH

DEPTH-FIRST SEARCH OF A DIRECTED GRAPH

A **depth-first search** uses a **stack** (or recursion) instead of a queue. We define predecessors and colour vertices as in BFS. It is also useful to specify a **discovery time** $d[v]$ and a **finishing time** $f[v]$ for every vertex v . We increment a **time counter** every time a value $d[v]$ or $f[v]$ is assigned. We eventually visit all the vertices, and the algorithm constructs a **depth-first forest**.

DEPTH FIRST SEARCH ALGORITHM

```

1 global variables:
2   pred[1..n] = [null, null, ..., null]
3   colour[1..n] = [white, white, ..., white]
4   d[1..n] = [0, 0, ..., 0] // discovery times
5   f[1..n] = [0, 0, ..., 0] // finish times
6   time = 0
7
8 DepthFirstSearch(adj[1..n])
9   for v = 1..n
10    if colour[v] == white
11      DFSVisit(v)
12
13 DFSVisit(adj[1..n], v)
14   colour[v] = gray
15   time = time + 1
16   d[v] = time
17
18   for each w in adj[v]
19     if colour[w] == white
20       pred[w] = v
21       DFSVisit(w)
22
23   colour[v] = black
24   time = time + 1
25   f[v] = time
  
```

Example execution starting at node 1

time = 12

DFS TREE / FOREST

As in breadth first search, $pred[]$ induces a **forest**

Let's match the graph's edge directions (opposite from pred)

Could draw BFS forest this way also...

Each top level DFSVisit call is the root of a tree

Recall: DFSVisit(1), DFSVisit(6)

BASIC DFS PROPERTIES TO REMEMBER

Nodes start **white**

A node v turns **gray** when it is **discovered**, which is when the first call to $DFSVisit(v)$ happens

After v is turned **gray**, we recurse on its neighbours

After recursing on **all neighbours**, we turn v **black**

Recursive calls on neighbours end before $DFSVisit(v)$ does, so the neighbours of v turn black before v

Also gets a **discovery time** $d[v]$ at this point

Also gets a **finish time** $f[v]$ at this point

RUNTIME COMPLEXITY OF DFS (FOR ADJ. LISTS)

```

1 global variables:
2 pred[1..n] = [null, null, ..., null]
3 colour[1..n] = [white, white, ..., white]
4 d[1..n] = [0, 0, ..., 0] // discovery times
5 f[1..n] = [0, 0, ..., 0] // finish times
6 time = 0
7
8 DepthFirstSearch(adj[1..n])
9 for v = 1..n
10   if colour[v] == white
11     DFSVisit(v)
12
13 DFSVisit(adj[1..n], v)
14   colour[v] = gray
15   time = time + 1
16   d[v] = time
17
18   for each w in adj[v]
19     if colour[w] == white
20       pred[w] = v
21       DFSVisit(w)
22
23   colour[v] = black
24   time = time + 1
25   f[v] = time
    
```

$O(n)$

Home exercise: complexity with adjacency matrix?

Only called on a white node, and immediately colours the node gray

So called **once per node!**

Each call iterates over the neighbours. Effectively: "for each node, for each neighbour, do $O(1)$ work + recurse."

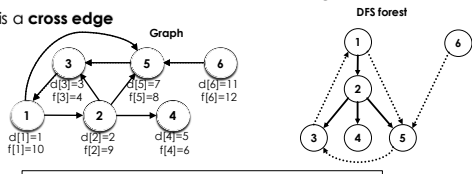
Total $O(n+m)$ iterations over all recursive calls. **Total $O(n+m)$ runtime!**

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CLASSIFYING EDGE $u \rightarrow v$ IN DFS

- If $pred[v] = u$, then: (u, v) is a **tree edge**
- Else if v is a **descendant** of u in the DFS forest: **forward edge**
- Else if v is an **ancestor** of u in the DFS forest: **back edge**
- Else: (u, v) is a **cross edge**

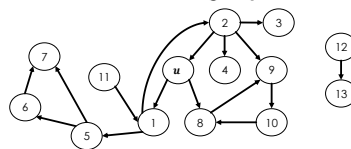


Can we classify edges **without** inspecting the DFS forest? Perhaps using $d[\dots]$, $f[\dots]$, $colour[\dots]$?

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DEFINITIONS

- Definition:** we use I_u to denote $(d[u], f[u])$, which we call the **interval of u**
- Definition:** v is **white-reachable** from u if there is a path from u to v containing **only white nodes** (excluding u)

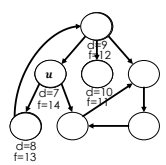


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EXPLORING $D[]$, $F[]$ AND $COLOUR[]$

Observe: every node v that is **white-reachable** from u when we first call $DFSVisit(u)$ becomes **gray after u** and **black before u** (so I_v is **nested inside** I_u)

- Start $DFSVisit(u)$, colour u grey, and set u 's discovery time
- Perform $DFSVisit$ calls recursively...
- Colour u black, set u 's finish time and return from $DFSVisit(u)$



Consider the tree of recursive calls rooted at $DFSVisit(u)$.
v is discovered by a call in this tree iff I_v is nested inside I_u
iff v is a descendant of u in the DFS forest
iff v turns grey after u and black before u
iff v is white-reachable from u when $DFSVisit(u)$ is called

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SUMMARIZING IN A THEOREM

- Theorem:** Let u, v be any nodes. The following statements are all **equivalent**:
 - $(v$ is **white-reachable** from u when we call $DFSVisit(u)$)
 - $(v$ turns grey after u and black before u)
 - $($ discovery/finish time interval I_v is **nested inside** $I_u)$
 - $(v$ is discovered during $DFSVisit(u)$)
 - $(v$ is a **descendant of u** in the DFS forest)

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CLASSIFYING EDGE TYPES IN DFS

DFS inspects **every edge** in the graph.

When DFS inspects an edge $\{u, v\}$, the colour of v and relationship between the intervals of u and v determine the **edge type**.

edge type	colour of v	discovery/finish times	relationship
tree	Q1?	Q2?	v is a child of u in the DFS tree
forward	Q4?	Q3?	v is a descendant of u
back	Q6?	Q5?	v is an ancestor of u
cross	Q8?	Q7?	v is not a descendant, and not an ancestor

Recall: $\{v$ is discovered during $DFSvisit(u)$

- $\Leftrightarrow v$ is **white-reachable** from u when we call $DFSvisit(u)$
- $\Leftrightarrow v$ is a **descendant of u** in the DFS forest)
- $\Leftrightarrow v$ turns grey after u and black before u
- $\Leftrightarrow I_v$ nested inside I_u

Annotations:

- v discovered during $DFSvisit(u)$ but **not directly** from u (or $\{u, v\}$ would be a tree edge)
- So when $DFSvisit(u)$ inspects $\{u, v\}$, v **cannot** be white
- v is already discovered!
- ... by another recursive call that $DFSvisit(u)$ makes when it inspects a **previous edge**
- That call **terminates** before $DFSvisit(u)$ inspects $\{u, v\}$
- And it colors v **black!**

USEFUL FACT: PARENTHESIS THEOREM

Theorem: for each pair of nodes u, v the intervals of u and v are either **disjoint** or **nested**



Proof: Suppose the intervals are **not disjoint**.

- Then either $d[v] \in I_u$ or $d[u] \in I_v$
- WLOG suppose $d[v] \in I_u$
- Then v is discovered during $DFSvisit(u)$
- So, v must turn gray after u and black before u
- So $f[v] < f[u]$
- So **the intervals are nested**. QED

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CLASSIFYING EDGE TYPES IN DFS

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edge type	colour of v	discovery/finish times	relationship
tree	white	$d[u] < d[v] < f[v] < f[u]$	v is a child of u in the DFS tree
forward	black	$d[u] < d[v] < f[v] < f[u]$	v is a descendant of u
back	gray	$d[v] < d[u] < f[u] < f[v]$	v is an ancestor of u
cross	Q8?	Q7?	v is not a descendant, and not an ancestor

Recall: $\{v$ is discovered during $DFSvisit(u)$

- $\Leftrightarrow v$ is **white-reachable** from u when we call $DFSvisit(u)$
- $\Leftrightarrow v$ is a **descendant of u** in the DFS forest)
- $\Leftrightarrow v$ turns grey after u and black before u
- $\Leftrightarrow I_v$ nested inside I_u

Annotations:

- So, I_v must be earlier.
- If I_u were earlier, then v would be discovered before u finishes (because of edge $\{u, v\}$), so intervals would not be disjoint!
- Intervals I_u and I_v must be **disjoint**. But which is **earlier**?

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CLASSIFYING EDGE TYPES IN DFS

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When DFS inspects an edge $\{u, v\}$, the colour of v and relationship between the intervals of u and v determine the **edge type**.

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back	gray	$d[v] < d[u] < f[u] < f[v]$	v is an ancestor of u
cross	black	$d[v] < f[v] < d[u] < f[u]$	v is not a descendant, and not an ancestor

Recall: $\{v$ is discovered during $DFSvisit(u)$

- $\Leftrightarrow v$ is **white-reachable** from u when we call $DFSvisit(u)$
- $\Leftrightarrow v$ is a **descendant of u** in the DFS forest)
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Annotations:

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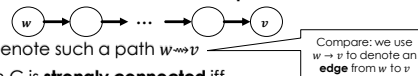
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APPLICATION OF DFS (OR BFS): STRONG CONNECTEDNESS

Testing existence of all-to-all paths

STRONG CONNECTEDNESS

- In a directed graph,
 - v is **reachable from w** if there is a **path** from w to v



- we denote such a path $w \rightsquigarrow v$
- A graph G is **strongly connected** iff every node is **reachable** from every other node
- More formally: $\forall w, v \in W \rightsquigarrow v$

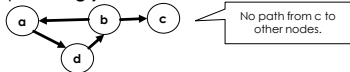
Compare: we use $w \rightarrow v$ to denote an edge from w to v

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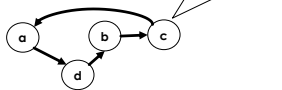
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STRONG CONNECTEDNESS

Is this graph **strongly connected**?



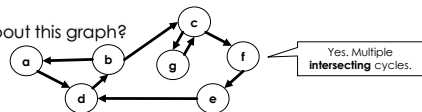
How about this one? Yes. One big cycle.



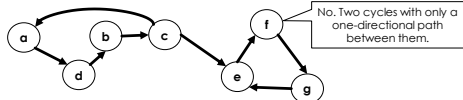
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STRONG CONNECTEDNESS

How about this graph?



How about this one?



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OTHER APPLICATIONS OF CHECKING STRONG CONNECTEDNESS

- You gain some **symmetry** from knowing a graph is strongly connected
- For example, you can **start a graph traversal at any node**, and know the traversal will reach **every node**
- Without strong connectedness, if you want to run a graph traversal that reaches every node in a single pass, you would have to do additional processing to determine an appropriate starting node

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OTHER APPLICATIONS OF CHECKING STRONG CONNECTEDNESS

- Useful as a sanity check!
- Suppose you want to run an algorithm that **requires strong connectedness**, and you **believe** your input graph is strongly connected
- Validate** your input by **testing** whether this is true!
- Subtle, difficult-to-detect bugs often result if such an algorithm is run only on one component of a graph
- [More concrete applications once we generalize and talk about strongly connected **components**...]

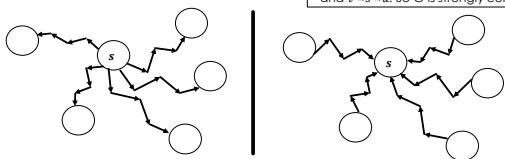
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A USEFUL LEMMA

- Lemma: a graph is strongly connected **iff** for any node s , **all nodes are reachable** from s , and s is **reachable** from all nodes

Proof: (\Rightarrow) Suppose G is strongly connected. Then for all u, v we have $u \rightarrow v$. Fix any s . Node s is reachable from all nodes, and vice versa.

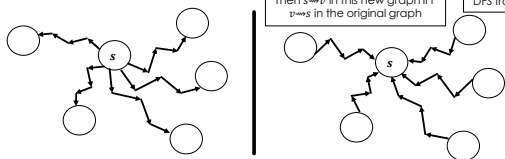
(\Leftarrow) Suppose some s is reachable from all nodes and vice versa. For any u, v , we have $u \rightarrow s \rightarrow v$, and $v \rightarrow s \rightarrow u$. So G is strongly conn.



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CREATING AN ALGORITHM

- How to use DFS to determine whether **every node is reachable** from a given node s ? DFS from s and see if every node turns black.
- How to use DFS to determine whether **s is reachable** from every node? What if we first **reverse** the direction of every edge? Then $s \rightarrow v$ in this new graph IFF $v \rightarrow s$ in the original graph. DFS from s .

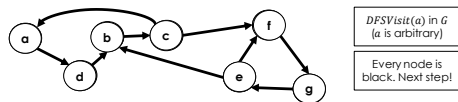


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THE ALGORITHM

- $IsStronglyConnected(G = \{V, E\})$ where $V = v_1, v_2, \dots, v_n$
 - $(colour, d, f) := DFSVisit(v_1, G)$
 - for $i := 1..n$
 - if $colour[v_i] \neq black$ then return *false*
 - Construct graph H by **reversing** all edges in G How?
 - $(colour, d, f) := DFSVisit(v_1, H)$
 - for $i := 1..n$
 - if $colour[v_i] \neq black$ then return *false*
 - return *true*

EXAMPLE EXECUTION 1



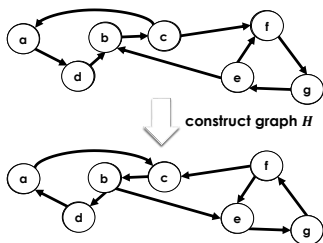
$DFSVisit(a)$ in G
(a is arbitrary)

Every node is black. Next step!

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EXAMPLE EXECUTION 1



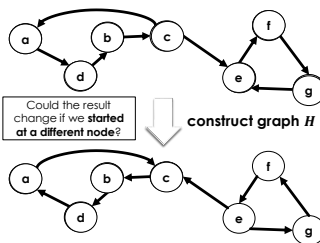
$DFSVisit(a)$ in G
(a is arbitrary)

Every node is black. Next step!

$DFSVisit(a)$ in H

Every node is black. So G is strongly connected!

EXAMPLE EXECUTION 2



$DFSVisit(a)$ in G
(a is arbitrary)

Every node is black. Next step!

Could the result change if we started at a different node?

$DFSVisit(a)$ in H

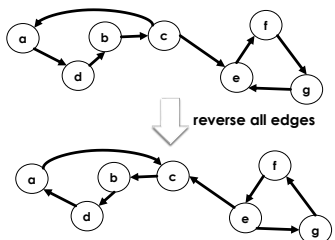
Some nodes are **not black**

No path from those nodes to a . So G is **not strongly connected!**

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REVERSING EDGES: ADJACENCY MATRIX

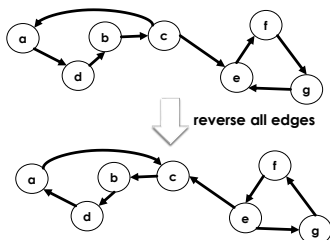


	target						
source	a	b	c	d	e	f	g
a	1						
b		1					
c	1		1				
d		1		1			
e					1		
f						1	
g							1

	target						
source	a	b	c	d	e	f	g
a							
b			1				
c	1						
d		1					
e						1	
f							1
g							

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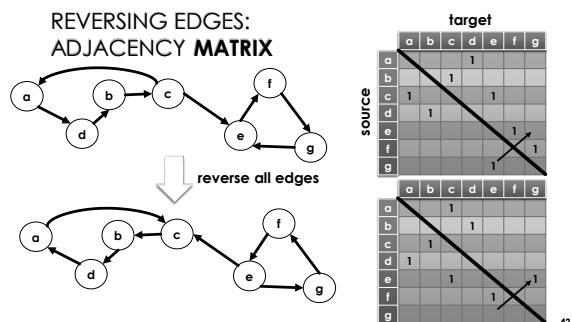
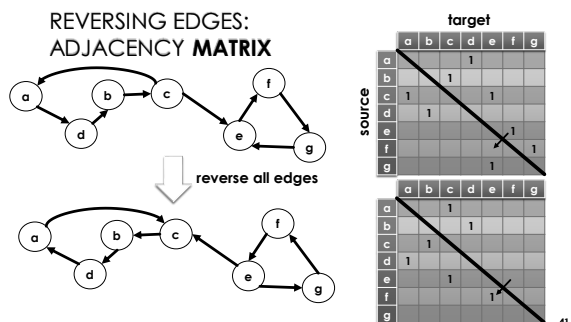
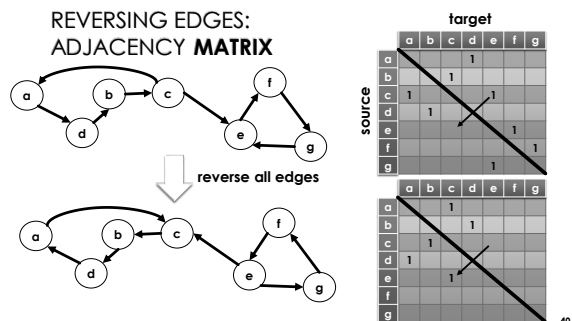
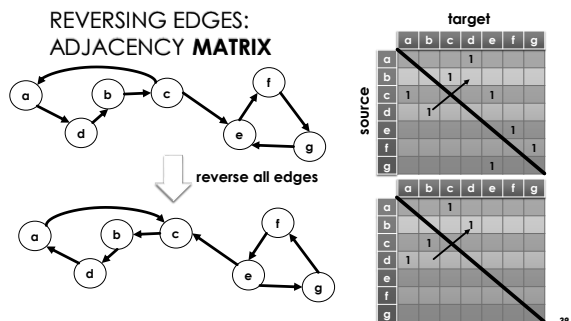
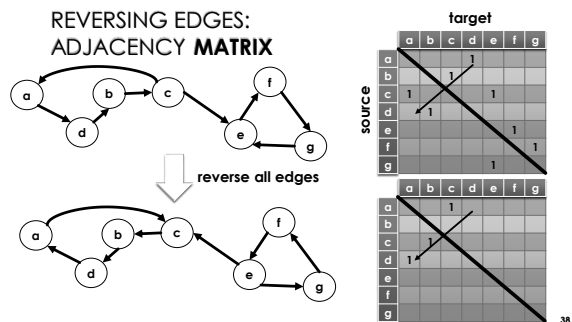
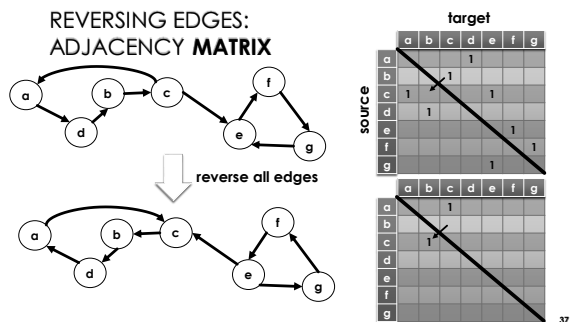
REVERSING EDGES: ADJACENCY MATRIX



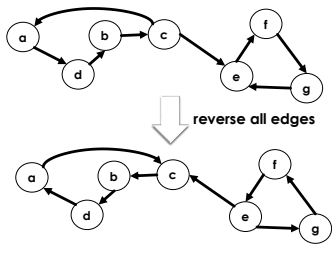
	target						
source	a	b	c	d	e	f	g
a	1						
b		1					
c	1		1				
d		1		1			
e					1		
f						1	
g							1

	target						
source	a	b	c	d	e	f	g
a							
b			1				
c	1						
d		1					
e						1	
f							1
g							

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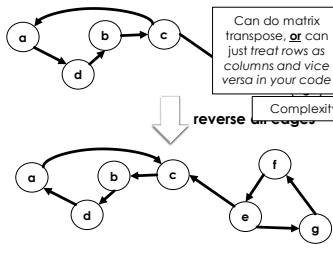
REVERSING EDGES: ADJACENCY MATRIX



	target						
source	a	b	c	d	e	f	g
a							
b							
c	1						
d	1						
e							
f							
g							

	target						
source	a	b	c	d	e	f	g
a							
b							
c							
d							
e							
f							
g							

REVERSING EDGES: ADJACENCY MATRIX



	target						
source	a	b	c	d	e	f	g
a							
b							
c	1						
d	1						
e							
f							
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	target						
source	a	b	c	d	e	f	g
a							
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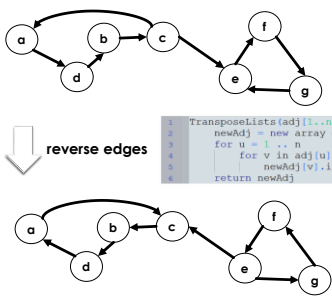
Can do matrix transpose, or can just treat rows as columns and vice versa in your code

Complexity?

M_E

$(M_E)^T$

REVERSING EDGES: ADJACENCY LISTS



source	target
a	d
b	c
c	a, e
d	b
e	f, g
f	a
g	e

source	target
a	c
b	d
c	b
d	a
e	c, g
f	e
g	f

```

1 TransposeLists(adj[1..n])
2 newAdj = new array of n lists
3 for u = 1..n
4   for v in adj[u]
5     newAdj[v].insert(u)
6 return newAdj
    
```

Complexity?

RUNTIME COMPLEXITY FOR ADJACENCY LIST REPRESENTATION?

- IsStronglyConnected($G = \{V, E\}$) where $V = v_1, v_2, \dots, v_n$
 - $(colour, d, f) := DFSVisit(v_1, G)$
 - for $i := 1..n$
 - if $colour[v_i] \neq black$ then return false
 - Construct graph H by reversing all edges in G
 - $(colour, d, f) := DFSVisit(v_1, H)$
 - for $i := 1..n$
 - if $colour[v_i] \neq black$ then return false
 - return true

$O(n + m)$