

# CS 341: ALGORITHMS

**Lecture 20: intractability II – complexity class NP**

Readings: see website

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# THIS TIME

- **Finishing TSP reductions**
- Complexity class **NP**
  - Oracles, certificates, polytime verification algorithms



# RECALL

- So far we know
  - $\text{TSP-Dec} \leq_P^T \text{TSP-Optimal Value}$
  - $\text{TSP-Dec} \leq_P^T \text{TSP-Optimization}$
- **In progress**
  - **$\text{TSP-Optimal Value} \leq_P^T \text{TSP-Dec}$**

## Travelling Salesperson Problems

### Problem 7.5

#### TSP-Optimization

**Instance:** A graph  $G$  and edge weights  $w : E \rightarrow \mathbb{Z}^+$ .

**Find:** A hamiltonian cycle  $H$  in  $G$  such that  $w(H) = \sum_{e \in H} w(e)$  is minimized.

### Problem 7.6

#### TSP-Optimal Value

**Instance:** A graph  $G$  and edge weights  $w : E \rightarrow \mathbb{Z}^+$ .

**Find:** The minimum  $T$  such that there exists a hamiltonian cycle  $H$  in  $G$  with  $w(H) = T$ .

### Problem 7.7

#### TSP-Decision

**Instance:** A graph  $G$ , edge weights  $w : E \rightarrow \mathbb{Z}^+$ , and a target  $T$ .

**Question:** Does there exist a hamiltonian cycle  $H$  in  $G$  with  $w(H) \leq T$ ?

What's the size of the input  $I = (G, w)$ ?

$$Size(I) = Size(G) + Size(w)$$

So, suppose  $G$  is represented as an **array of adjacency lists** (one list for each vertex), with each list containing **edges** to neighbouring vertices, and an edge is represented by a **weight** and the **name** of the target vertex

**Bits** to store **weight** of the edge  
(storing  $w(e)$  takes  $\log w(e) + 1$  bits)

**Bits** to store the **name** of the target vertex (in  $1..|V|$ )

$$Size(I) = |V| + \sum_{e \in E} (\log w(e) + 1 + \log|V| + 1)$$

**Array** of empty lists for all vertices  $v$

**For all edges**

Let's relate this to runtime... what's the runtime?



# TSP-Optimal Value $\leq_{\substack{T \\ P}}^T$ TSP-Dec

Let's assume  $O(1)$  time for operations on weights

Technically not needed to show polytime.. But simplifies

**Algorithm:** *TSP-OptimalValue-Solver*( $G, w$ )

**external** *TSP-Dec-Solver*

$hi \leftarrow \sum_{e \in E} w(e)$   $O(|E|)$

$lo \leftarrow 0$   $O(1)$

**if not** *TSP-Dec-Solver*( $G, w, hi$ ) **then return**  $(\infty)$   $O(1)$  for the oracle

**while**  $hi > lo$  # iterations:  $O(\log(hi - lo))$

**do**  $\left\{ \begin{array}{l} mid \leftarrow \lfloor \frac{hi+lo}{2} \rfloor \\ \text{if } TSP-Dec-Solver(G, w, mid) \\ \text{then } hi \leftarrow mid \\ \text{else } lo \leftarrow mid + 1 \end{array} \right.$   $\left. \begin{array}{l} = \log \sum_{e \in E} w(e) \\ O(1) \end{array} \right\}$

**return** ( $hi$ )

Runtime  $T(I) \in O(|E| + \log \sum_{e \in E} w(e))$

# COMPARING $T(I)$ AND $Size(I)$

- $T(I) \in O(|E| + \log \sum_{e \in E} w(e))$
- $Size(I) = |V| + \sum_{e \in E} (\log w(e) + 1 + \log |V| + 1)$   
 $= |V| + \sum_{e \in E} (\log w(e) + 1) + \sum_{e \in E} (\log |V| + 1)$   
 $= |V| + \sum_{e \in E} (\log w(e) + 1) + \sum_{e \in E} (\log |V|) + |E|$
- Want to show  $T(I) \in O(Size(I)^c)$  for some constant  $c$  (we show  $c=1$ )  
 $O(|E| + \log \sum_{e \in E} w(e)) \stackrel{?}{\subseteq} O(|V| + \sum_{e \in E} (\log w(e) + 1) + \sum_{e \in E} \log |V| + |E|)$   
 $\Leftrightarrow O(\log \sum_{e \in E} w(e)) \stackrel{?}{\subseteq} O(|V| + \sum_{e \in E} (\log w(e) + 1) + \sum_{e \in E} \log |V|)$   
**How to compare  $\log \sum_{e \in E} w(e)$  and  $\sum_{e \in E} (\log w(e) + 1)$ ?**



# COMPARING $T(I)$ AND $Size(I)$

- How to compare  $\log \sum_{e \in E} w(e)$  and  $\sum_{e \in E} (\log w(e) + 1)$ ?
- $\sum_{e \in E} (\log w(e) + 1) = (\log w(e_1) + 1) + (\log w(e_2) + 1) + \dots + (\log(w(e_{|E|})) + 1)$
- Can we combine these terms into one log using  $\log x + \log y = \log xy$ ?
- $\sum_{e \in E} (\log w(e) + 1) = (\log w(e_1) + \log 2) + \dots + (\log(w(e_{|E|})) + \log 2)$
- $\sum_{e \in E} (\log w(e) + 1) = \log 2w(e_1) 2w(e_2) \dots 2w(e_{|E|}) = \log \prod_{e \in E} 2w(e)$
- So how to compare  $\log \prod_{e \in E} 2w(e)$  and  $\log \sum_{e \in E} w(e)$ ?
  - All  $w(e)$  are positive integers, so  $\prod_{e \in E} 2w(e) \geq \sum_{e \in E} w(e)$
  - Since log is increasing on  $\mathbb{Z}^+$ ,  $\log \prod_{e \in E} 2w(e) \geq \log \sum_{e \in E} w(e)$



# COMPARING $T(I)$ AND $Size(I)$

- We in fact show  $T(I) \in O(Size(I))$

$$O(\log \sum_{e \in E} w(e)) \stackrel{?}{\subseteq} O(|V| + \sum_{e \in E} (\log w(e) + 1) + \sum_{e \in E} \log |V|)$$

**How to compare  $\log \sum_{e \in E} w(e)$  and  $\sum_{e \in E} (\log w(e) + 1)$ ?**

We just saw  $\sum_{e \in E} (\log w(e) + 1) = \log \prod_{e \in E} 2w(e) \geq \log \sum_{e \in E} w(e)$

**So  $T(I) \in O(Size(I)^c)$  where  $c = 1$**

**So this reduction has runtime that is polynomial in the input size!**



**TSP-Optimal Value**  $\leq_{\substack{T \\ P}}^T$  **TSP-Dec**

**Algorithm:** *TSP-OptimalValue-Solver*( $G, w$ )  
**external** *TSP-Dec-Solver*  
 $hi \leftarrow \sum_{e \in E} w(e)$   
 $lo \leftarrow 0$   
**if not** *TSP-Dec-Solver*( $G, w, hi$ ) **then return** ( $\infty$ )  
**while**  $hi > lo$   
  **do**  $\left\{ \begin{array}{l} mid \leftarrow \lfloor \frac{hi+lo}{2} \rfloor \\ \text{if } TSP-Dec-Solver(G, w, mid) \\ \quad \text{then } hi \leftarrow mid \\ \quad \text{else } lo \leftarrow mid + 1 \end{array} \right.$   
**return** ( $hi$ )

So TSP-OptimalValue-Solver is polytime... But is it a correct reduction from TSP-Optimal Value to TSP-Dec?

**Need to prove:**  
TSP-OptimalValue-Solver( $G, w$ )  
returns the weight  $W$   
of the **shortest Hamiltonian Cycle (HC)** in  $G$

**Sketch:** We return  $\infty$  iff there is **no HC**.  
**Key loop invariant:**  $W \in [lo, hi]$ .  
So, at termination when  $hi = lo$ ,  
we return exactly  $hi = W$ .

# TSP-Optimal Value $\leq_P^T$ TSP-Dec

**Algorithm:** *TSP-OptimalValue-Solver*( $G, w$ )

**external** *TSP-Dec-Solver*

$hi \leftarrow \sum_{e \in E} w(e)$

$lo \leftarrow 0$

**if not** *TSP-Dec-Solver*( $G, w, hi$ ) **then return** ( $\infty$ )

**while**  $hi > lo$

**do**  $\left\{ \begin{array}{l} mid \leftarrow \lfloor \frac{hi+lo}{2} \rfloor \\ \text{if } TSP-Dec-Solver(G, w, mid) \\ \text{then } hi \leftarrow mid \\ \text{else } lo \leftarrow mid + 1 \end{array} \right.$

**return** ( $hi$ )

So, TSP-OptimalValue-Solver is **polytime**,  
and is a **correct** reduction.

We have therefore shown:  
**TSP-Optimal Value is polytime  
reducible to TSP-Dec**

So, if an  $O(1)$  implementation of TSP-Dec-Solver  
exists, then we have a **polytime** implementation of  
TSP-Optimal-Value-Solver!

In fact, TSP-OptimalValue-Solver remains  
**polytime** even if the implementation of the  
**oracle runs in polytime** instead of  $O(1)$ ! (bonus slides)



# PROVING REDUCTIONS CORRECT

- **In more complex reductions** where we **transform the input** before calling the oracle, we will need a **more complex proof**:
- (A) If there is a(n optimal) solution in the input, our transformation will preserve that solution so the oracle can find it, and
- (B) Our transformation doesn't introduce new solutions that are **not** present in the original input
  - *(i.e., if we find a solution in the transformed input, there was a corresponding solution in the original input)*

More on this later...

# INPUT SIZE CHEAT SHEET

**Exponentially** larger than optimal representation!

Input $I$	Perfectly fine choices of $Size(I)$
int $x$	1 or $\lfloor \log(x) \rfloor + 1$ <b>(can simplify to <math>\log(x) + 1</math> or <math>\log x</math>)</b>
Graph $(V, E)$ with weights $W$ :	$ V $ or $ E $ or $ V ^2$ or $ V  +  E $ or $\sum_{e \in E} (\log(w(e)) + 1)$ or $\sum_{u, v \in V} (\log(w(u, v)) + 1)$ or <b>any sum of terms above</b>
$A[1..n]$ of int	$n$ or $\sum_i (\log(A[i]) + 1)$
$n \times n$ matrix $m$	$n^2$ or $\sum_{i, j} (\log(m_{ij}) + 1)$

To write down  $x=1$ , need  $\log(1)+1=1$  bit.  
For  $x=2$  this is 2 bits.  
For  $x=4$ , 3 bits.

Pick any expression that makes your analysis easy

Input $I$	Examples of <b><u>BAD</u></b> choices of $Size(I)$
int $x$	$x$
Graph $(V, E)$	$2^{ V }$ or $ V ^{ E }$ or $\sum_{e \in E} w(e)$
$A[1..n]$ of int	$2^n$ or $\sum_i A[i]$

**Pseudo-polynomial**  $\sim$  no exponentiation of non-constant terms

Technically any **pseudo-polynomial combination** of these terms is fine.  
For example, the following is fine:  
 $(|E|^{100} + |V|^2) \cdot \sum_{e \in E} (\log(w(e)) + 1)$



- So far we know
  - $\text{TSP-Dec} \leq_{\mathcal{P}}^T \text{TSP-Optimal Value}$
  - $\text{TSP-Dec} \leq_{\mathcal{P}}^T \text{TSP-Optimization}$
  - $\text{TSP-Optimal Value} \leq_{\mathcal{P}}^T \text{TSP-Dec}$
- Let's show
  - $\text{TSP-Optimization} \leq_{\mathcal{P}}^T \text{TSP-Dec}$

# WHAT ABOUT REDUCING TSP-OPTIMIZATION TO TSP-DEC?

## Problem 7.5

### TSP-Optimization

**Instance:** A graph  $G$  and edge weights  $w : E \rightarrow \mathbb{Z}^+$ .

**Find:** A hamiltonian cycle  $H$  in  $G$  such that  $w(H) = \sum_{e \in H} w(e)$  is minimized.

Need to return the **actual** minimum Hamiltonian Cycle!

We already know how to get the **weight  $T^*$**  of the minimum HC...

## Problem 7.7

### TSP-Decision

**Instance:** A graph  $G$ , edge weights  $w : E \rightarrow \mathbb{Z}^+$ , and a target  $T$ .

**Question:** Does there exist a hamiltonian cycle  $H$  in  $G$  with  $w(H) \leq T$ ?

Given only a **single bit** of information **per call** to the oracle

Idea: Use  **$T^*$**  along with calls to the oracle to somehow figure out **which edges** are involved in the minimum HC?



# TSP-Optimization $\leq_P^T$ TSP-Dec

**Algorithm:** *TSP-Optimization-Solver*( $G = (V, E), w$ )  
**external** *TSP-OptimalValue-Solver*, *TSP-Dec-Solver*  
 $T^* \leftarrow \text{TSP-OptimalValue-Solver}(G, w)$   
**if**  $T^* = \infty$  **then return** ("no hamiltonian cycle exists")  
 $w_0 \leftarrow w$   
 $H \leftarrow \emptyset$   
**for all**  $e \in E$   
**do**  $\begin{cases} w_0[e] \leftarrow \infty \\ \text{if not } \text{TSP-Dec-Solver}(G, w_0, T^*) \\ \text{then } \begin{cases} w_0[e] \leftarrow w[e] \\ H \leftarrow H \cup \{e\} \end{cases} \end{cases}$   
**return** ( $H$ )

To remove any dependence on this "other oracle," simply replace this call with the reduction **code** we showed

Already know this call is poly-time reducible to TSP-Dec!

If removing edge  $e$  removes **every** Hamiltonian cycle of minimum weight

then  $e$  is part of **every** minimum Hamiltonian cycle, and we add it to  $H$  (and add it back into the graph)

At the end, the graph contains precisely the edges that are needed to produce a minimum HC

[Correctness] **Loop invariant:** there exists a HC of weight  $T^*$  in  $w_0$

By the end of the loop,  $H$  contains all finite edges in  $w_0$

So some HC  $C$  of weight  $T^*$  **is contained in**  $H$

At the end of the algorithm, there is a Hamiltonian Cycle  $\mathcal{C}$  of optimal weight  $T^*$  **contained in**  $H$

If  $H$  is **precisely**  $\mathcal{C}$ , then we are done.  
**Suppose not** to obtain a contradiction.

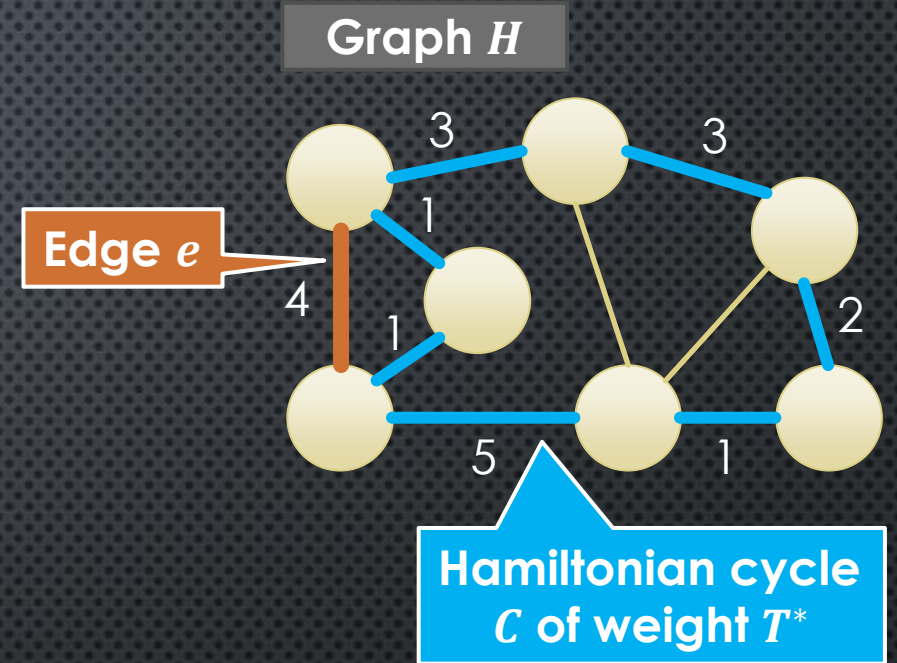
In this case, there are some **other edges** in  $H$  as well.

Let  $e$  be one such edge.

Consider the iteration when  $e$  was processed.  
Note  $e$  was **not removed** in this iteration!

Doing so would remove **all** Hamiltonian Cycles of weight  $T^*$ ,  
**including**  $\mathcal{C}$ .

This means the edge must be part of  $\mathcal{C}$ ---contradiction!





# TSP-Optimization $\leq_P^T$ TSP-Dec

**Algorithm:** *TSP-Optimization-Solver*( $G = (V, E), w$ )

**external** *TSP-OptimalValue-Solver*, *TSP-Dec-Solver*

$T^* \leftarrow$  *TSP-OptimalValue-Solver*( $G, w$ )  $\leftarrow$   $poly(Size(I))$

**if**  $T^* = \infty$  **then return** ("no hamiltonian cycle exists")

$w_0 \leftarrow w$   $\leftarrow$   $O(m)$  to copy matrix

$H \leftarrow \emptyset$   $\leftarrow$   $O(1)$  to create list

**for all**  $e \in E$   $\leftarrow$   $O(m)$  iterations

**do**  $\left\{ \begin{array}{l} w_0[e] \leftarrow \infty \\ \text{if not } TSP-Dec-Solver(G, w_0, T^*) \\ \text{then } \left\{ \begin{array}{l} w_0[e] \leftarrow w[e] \\ H \leftarrow H \cup \{e\} \end{array} \right. \end{array} \right.$   $\leftarrow$   $O(1)$  per iteration

**return** ( $H$ )

So this is a **correct** reduction.  
Is it a **polytime reduction**?

**What's the runtime?**

Let's assume unit costs for simplicity

Runtime =  $poly(Size(I)) + O(m)$

**What's  $Size(I)$ ?**

(What's a "useful" lower bound?)

$Size(I) = \Omega(|E|) = \Omega(m)$

Clearly  $O(m) \in O(Size(I)^1)$   
So runtime is in  $poly(Size(I))$

So **yes**, this is a **polytime reduction**

What would change if we precisely counted the number of bits in each edge, weight, etc., in  $Size(I)$ ?

What if **operations on weight  $w$**  took  $O(\log w)$  time? (bonus slides)

# RECAP

- Showed three flavours of TSP are **polytime-equivalent** (i.e., if you can solve one flavour in polytime, you can solve all three flavours in polytime)
  - One of these was a decision problem (yes/no), and the other two were not (total weight, actual cycle)
- **Decision and non-decision flavours** of a problem are often polytime-equivalent
- Proofs for a **polytime Turing reduction**
  - **Correctness** (return value is correct for every possible input)
  - **Polytime** (runtime is polynomial in the input size)  
[or poly(some lower bound on the input size)]



Note: only one of my  
sections got here

# COMPLEXITY CLASS NP

**NP: Non-deterministic polynomial time**

# EXAMPLE: SUBSET-SUM PROBLEM

- Suppose we are given some integers, -7, -3, -2, 5, 8
- Does **some** subset of these **sum to zero**?
  - In this case, yes:  $(-3) + (-2) + 5 = 0$

Finding such a subset can be extremely difficult

Suppose I give you a **certificate** consisting of an array of numbers, and **claim** it represents such a subset

Of course, I might lie and give you a subset that does **not sum to zero**...

If I'm telling the truth, then we call this a **yes-certificate**. It is essentially a **proof** that "yes" is the correct output.

I could even give you numbers that are **not in the input**...

Can you use a yes-certificate to solve the problem efficiently?

Can you determine whether I am lying in polynomial time?



# SUBSET-SUM VIA NON-DETERMINISTIC ORACLE

- Suppose there is a **non-deterministic oracle**, which returns **a subset that sums to 0 if one exists** and otherwise can return **anything (even garbage)**
- We call the oracle's output a **certificate**
- Given a **certificate**, can you **verify in polytime** whether it describes a solution to the problem?

```
1 SubsetSumWithOracle(I)
2   C = Oracle(I)
3   return verify(I, C)
4
5 verify(I, C)
6   if C not subset of I then return false
7   return (sum(C) == 0)
```

Given such an oracle, this algorithm would **solve** subset-sum

Otherwise, either C is not a subset of the input (return false), or C sums to a non-zero value (return false)

If there **exists** a subset that sums to 0, then **C** is one such subset, and we return **true**

**“Non-deterministic”** is the **N** in **NP**, and it is so named because of oracles

Here **“non-deterministic”** just means the oracle is magically guaranteed to return a yes-certificate if one exists

# BONUS SLIDES



# TSP-Optimal Value $\leq \frac{T}{P}$ TSP-Dec

**Algorithm:** *TSP-OptimalValue-Solver*( $G, w$ )

**external** *TSP-Dec-Solver*

$hi \leftarrow \sum_{e \in E} w(e)$

$lo \leftarrow 0$

**if not** *TSP-Dec-Solver*( $G, w, hi$ ) **then return** ( $\infty$ )

**while**  $hi > lo$

**do**  $\left\{ \begin{array}{l} mid \leftarrow \lfloor \frac{hi+lo}{2} \rfloor \\ \text{if } TSP-Dec-Solver(G, w, mid) \\ \text{then } hi \leftarrow mid \\ \text{else } lo \leftarrow mid + 1 \end{array} \right.$

**return** ( $hi$ )

TSP-OptimalValue-Solver remains **polytime** even if the **oracle runs in polytime** instead of  $O(1)$ !

**The key idea is:** Consider polynomials  $P_R(s)$  and  $P_O(s)$  representing the runtime of a reduction and its oracle, respectively, on an input of size  $s$ .

**Worst possible runtime** happens if **every step** in the reduction is a call to the oracle.

**This is  $P_R(s)P_O(s)$  --- multiplication of polynomials.**

But **multiplying polynomials** of degrees  $d_1, d_2$  **results in a polynomial** of degree  $\leq d_1 + d_2$ . **Example:**

$$P_1(x) = 5x^2 + 10x + 100$$

$$P_2(x) = 20x^3 + 20$$

$$\begin{aligned} P_1(x)P_2(x) &= (5x^2 + 10x + 100)(20x^3 + 20) \\ &= 100x^5 + 200x^4 + 2000x^3 + 100x^2 + 200x + 2000 \end{aligned}$$

Let's assume  $O(\log w)$  time for reading/writing/arithmetic operations on each weight  $w$  (and  $O(\log w)$  space).

**Algorithm:**  $TSP\text{-}Optimization\text{-}Solver(G = (V, E), w)$

**external**  $TSP\text{-}OptimalValue\text{-}Solver, TSP\text{-}Dec\text{-}Solver$   
 $T^* \leftarrow TSP\text{-}OptimalValue\text{-}Solver(G, w)$

**if**  $T^* = \infty$  **then return** ("no hamiltonian cycle exists")

$w_0 \leftarrow w$   $O(\sum_{u,v \in V} \log w(u, v))$  to copy matrix  $O(1)$

$H \leftarrow \emptyset$   $O(1)$  to create list

**for all**  $e \in E$   $O(m)$  iterations: **for all**  $u, v$

**do**  $w_0[e] \leftarrow \infty$   $O(\log w(u, v))$   
**if not**  $TSP\text{-}Dec\text{-}Solver(G, w_0, T^*)$   $O(1)$

**then**  $w_0[e] \leftarrow w[e]$   $O(\log w(u, v))$   
 $H \leftarrow H \cup \{e\}$   $O(1)$

**return** ( $H$ )

Suppose we show this is  $poly(Size(I))$

So this is a **correct** reduction.  
Is it a **polytime reduction**?

**What's the runtime on such an input?**

$$\text{Runtime} = poly(\text{Size}(I)) + O(m + \sum_{u,v \in V} \log w(u, v))$$

**What's  $Size(I)$ ? (or a useful lower bound on it)**

$$Size(I) = O(|E| + \sum_{u,v \in V} \log w(u, v))$$

Clearly  $O(m + \sum_{u,v \in V} \log w(u, v)) \in poly(Size(I))$

So, this is **still** a **polytime reduction**

Unit cost vs non-unit cost assumptions usually do **not** usually make a difference...

This should not be surprising, since the same  $O(\log w)$  terms are introduced into both space and time complexities...