Directed graphs

A directed graph consists of a collection of nodes (also called vertices) together with a collection of edges.

An edge is an ordered pair of nodes, which we can represent by an arrow from one node to another.

We have seen such graphs before. Evolution trees and expression trees were both directed graphs of a special type where an edge represented a parent-child relationship.

Graphs are a general data structure that can model many situations.

Computations on graphs form an important part of the computer science toolkit.
Graph terminology

Given an edge \((v, w)\), we say that \(w\) is an out-neighbour of \(v\), and \(v\) is an in-neighbour of \(w\).

A sequence of nodes \(v_1, v_2, \ldots, v_k\) is a path or route of length \(k - 1\) if \((v_1, v_2), (v_2, v_3), \ldots, (v_{k-1}, v_k)\) are all edges.

If \(v_1 = v_k\), this is called a cycle.

Directed graphs without cycles are called DAGs (directed acyclic graphs).

Representing graphs

We can represent a node by a symbol (its name), and associate with each node a list of its out-neighbours.

This is called the adjacency list representation.

More specifically, a graph is a list of pairs, each pair consisting of a symbol (the node’s name) and a list of symbols (the names of the node’s out-neighbours).

This is very similar to a parent node with a list of children.

> Our example as data

```scheme
(define G
  '((A (C D E))
    (B (E J))
    (C ())
    (D (F J))
    (E (K))
    (F (K H))
    (H ())
    (J (H))
    (K ())
  )
)```

To make our contracts more descriptive, we will define a Node and a Graph as follows:

;; A Node is a Sym

;; A Graph is one of:
;; * empty
;; * (cons (list v (list w_1 ... w_n)) g)
;; where g is a Graph
;;   v, w_1, ... w_n are Nodes
;;   v is the in-neighbour to w_1 ... w_n in the Graph
;;   v does not appear as an in-neighbour in g

;; graph-template: Graph → Any
(define (graph-template G)
  (cond
    [(empty? G) ...]
    [(cons? G)
      (... (first (first G)) ; first node in graph list
           ... (listof-node-template ; list of adjacent nodes
                 (second (first G)))
           ... (graph-template (rest G)) ...)]))

Finding paths

A path in a graph can be represented by the list of nodes on the path.

We wish to design a function find-path that consumes a graph plus origin and destination nodes, and produces a path from the origin to the destination, or false if no such path exists.

First we create an auxiliary function neighbours that consumes a node and a graph and produces the list of out-neighbours of the node.
> Neighbours in our example

(neighbours 'A G) ⇒ (list 'C 'D 'E)
(neighbours 'H G) ⇒ empty

(define G
  '(((A (C D E))
    (B (E J))
    (C ())
    (D (F J))
    (E (K))
    (F (K H))
    (H ())
    (J (H))
    (K ()))
)

> neighbhors

;; (neighbours v G) produces list of neighbours of v in G
;; neighbours: Node Graph → (listof Node)
;; requires: v is a node in G
(define (neighbours v G)
  (cond [(symbol=? v (first (first G))) (second (first G))]
        [else (neighbours v (rest G))]))

> Cases for find-path

Simple recursion does not work for find-path; we must use generative recursion.

If the origin equals the destination, the path consists of just this node.

Otherwise, if there is a path, the second node on that path must be an
out-neighbour of the origin node.

Each out-neighbour defines a subproblem (finding a path from it to the
destination).
Building a path from a solved sub-problem

In our example, any path from A to H must pass through C, D, or E.

If we knew a path from C to H, or from D to H, or from E to H, we could create one from A to H.

Backtracking algorithms

Backtracking algorithms try to find a path from an origin to a destination.

If the initial attempt does not work, such an algorithm “backtracks” and tries another choice.

Eventually, either a path is found, or all possibilities are exhausted, meaning there is no path.

Backtracking in our example

In our example, we can see the “backtracking” since the search for a path from A to H can be seen as moving forward in the graph looking for H.

If this search fails (for example, at C), then the algorithm “backs up” to the previous node (A) and tries the next neighbour (D).

If we find a path from D to H, we can just add A to the beginning of this path.
Exploring the list of out-neighbours

We need to apply `find-path` on each of the out-neighbours of a given node.

The `neighbours` function gives us a list of all the out-neighbours associated with that node.

This suggests writing `find-path/list` which consumes a list of nodes and will apply `find-path` to each one until it either finds a path to the destination or exhausts the list.

Mutual recursion

This is the same recursive pattern that we saw in the processing of expression trees and evolutionary trees.

For expression trees, we had two mutually recursive functions, `eval` and `apply`.

Here, we have two mutually recursive functions, `find-path` and `find-path/list`.

```
(define (find-path orig dest G)
  (cond [(symbol=? orig dest) (list dest)]
        [else (local [define
                      (define nbrs (neighbours orig G))
                      (define ?path (find-path/list nbrs dest G))]
                      (cond [((false? ?path) false]
                             [else (cons orig ?path)])]))])
```

We're using `?path` to mean it might hold a path or it might not.
> find-path/list

;; (find-path/list nbrs dest G) produces path from
;; an element of nbrs to dest in G, if one exists
;; find-path/list: (listof Node) Node Graph → (anyof (listof Node) false)
(define (find-path/list nbrs dest G)
  (cond [(empty? nbrs) false]
        [else (local [(define ?path (find-path (first nbrs) dest G))]
                  (cond [(false? ?path)
                             (find-path/list (rest nbrs) dest G)]
                        [else ?path]))]))

> Tracing (find-path 'A 'B G) (1/2)

If we wish to trace find-path, trying to do a linear trace would be very long, both in terms of steps and the size of each step. Our traces also are listed as a linear sequence of steps, but the computation in find-path is better visualized as a tree.

We will use an alternate visualization of the potential computation (which could be shortened if a path is found).

The next slide contains the trace tree. We have omitted the arguments dest and G which never change.
> Backtracking in implicit graphs (1/3)

The only places where real computation is done on the graph is in comparing the origin to the destination and in the `neighbours` function.

Backtracking can be used without having the entire graph available if the neighbours can be derived from a "configuration".

**Board games:**

![Board game example](https://www.puzzleprime.com/brain-teasers/deduction/eight-queens-puzzle/)

> Backtracking in implicit graphs (2/3)

Nodes typically represent configurations: (e.g. X's and O's played so far)

Edges represent ways in which one configuration becomes another: (e.g. the next player places an X or O)

The graph is acyclic if no configuration can occur twice in a game. This happens naturally when edges represent additions (tic-tac-toe, 8-queens, Sudoku).

![Graph example](https://www.geeksforgeeks.org/minimax-algorithm-in-game-theory-set-3-tic-tac-toe-ai-finding-optimal-move/)

> Backtracking in implicit graphs (3/3)

The `find-path` functions for implicit backtracking look very similar to those we have developed.

The neighbours function must now generate the set of neighbours of a node based on some description of that node (e.g. the placement of pieces in a game).

This allows backtracking in situations where it would be inefficient to generate and store the entire graph as data.

Backtracking in implicit graphs forms the basis of many artificial intelligence programs, though they generally add heuristics to determine which neighbour to explore first, or which ones to skip because they appear unpromising.

![Graph example](https://www.geeksforgeeks.org/minimax-algorithm-in-game-theory-set-3-tic-tac-toe-ai-finding-optimal-move/)
Termination of \texttt{find-path} (no cycles)

In a directed acyclic graph, any path with a given origin will recurse on its (finite number) of neighbours by way of \texttt{find-path/list}. The origin will never appear in this call or any subsequent calls to \texttt{find-path}: if it did, we would have a cycle in our DAG.

Thus, the origin will never be explored in any later call, and thus the subproblem is smaller. Eventually, we will reach a subproblem of size 0 (when all reachable nodes are treated as the origin).

Thus \texttt{find-path} always terminates for directed acyclic graphs.

> Non-termination of \texttt{find-path} (cycles)

It is possible that \texttt{find-path} may not terminate if there is a cycle in the graph.

Consider the graph . What if we try to find a path from A to D in this graph?

\[
\begin{align*}
\text{A} & \rightarrow \text{B} \\
\text{B} & \rightarrow \text{C} \\
\text{C} & \rightarrow \text{A} \\
\text{D} & \rightarrow \\
\end{align*}
\]

\[
(((\text{A (B)}) \\
(\text{B (C)}) \\
(\text{C (A)}) \\
(\text{D ())})
\]

> Non-termination of \texttt{find-path} (cycles)

\[
\begin{align*}
\text{(find-path 'A)} \\
\text{(find-path/list '(B))} \\
\text{(find-path 'B)} \\
\text{(find-path/list '(C))} \\
\text{(find-path 'C)} \\
\text{(find-path/list '(A))} \\
\text{(find-path 'A)} \\
\text{(find-path/list '(B))} \\
\end{align*}
\]

...
Paths v2: Handling cycles

We can use accumulative recursion to solve the problem of find-path possibly not terminating if there are cycles in the graph.

To make backtracking work in the presence of cycles, we need a way of remembering what nodes have been visited (along a given path).

Our accumulator will be a list of visited nodes.

We must avoid visiting a node twice.

The simplest way to do this is to add a check in find-path/list.

> find-path/list's accumulator

The code for find-path/list does not add anything to the accumulator (though it uses the accumulator).

Adding to the accumulator is done in find-path/acc which applies find-path/list to the list of neighbours of some origin node.

That origin node must be added to the accumulator passed as an argument to find-path/list.
;; find-path/acc: Node Node Graph (listof Node) →
;; (anyof (listof Node) false)
(define (find-path/acc orig dest G visited)
  (cond
   [(symbol=? orig dest) (list dest)]
   [else (local
          [(define nbrs (neighbours orig G))
           (define path (find-path/list nbrs dest G
                         (cons orig visited)))]
          (cond
           [(false? path) false]
           [else (cons orig path)]))]))

(define (find-path orig dest G) ;; new wrapper function
  (find-path/acc orig dest G '()))

Note that the value of the accumulator in find-path/list is always the reverse of
the path from A to the current origin (first argument).
This example has no cycles, so the trace only convinces us that we haven’t broken the function on acyclic graphs, and shows us how the accumulator is working.

But it also works on graphs with cycles.

The accumulator ensures that the depth of recursion is no greater than the number of nodes in the graph, so `find-path` terminates.

Backtracking now works on graphs with cycles, but it can be inefficient, even if the graph has no cycles.

If there is no path from the origin to the destination, then `find-path` will explore every path from the origin, and there could be an exponential number of them.
Paths v3: Efficiency

If there is no path from the origin to the destination, then find-path will explore every path from the origin, and there could be an exponential number of them.

If there are $d$ diamonds, then there are $3d + 2$ nodes in the graph, but $2^d$ paths from A to Y, all of which will be explored.

> Understanding the problem (1/2)

Applying find-path/acc to origin A results in find-path/list being applied to '(B1 B2), and then find-path/acc being applied to origin B1.

There is no path from B1 to Z, so this will produce false, but in the process, it will visit all the other nodes of the graph except B2 and Z.

find-path/list will then apply find-path/acc to B2, which will visit all the same nodes.

> Understanding the problem (2/2)

When find-path/list is applied to the list of nodes nbrs, it first applies find-path/acc to (first nbrs) and then, if that fails, it applies itself to (rest nbrs).

To avoid revisiting nodes, the failed computation should pass the list of nodes it has seen on to the next computation.

It will do this by returning the list of visited nodes instead of false when it fails to find a path. However, we must be able to distinguish this list from a successfully found path (also a list of nodes).
> Remembering what the list of nodes represents

We will encapsulate each kind of list in its own structure. We can then easily use the structure predicates to check whether the list of nodes represents a path (success) or visited nodes (failure).

```scheme
(define-struct success (path))
;; A Success is a (make-success (listof Node))

(define-struct failure (visited))
;; A Failure is a (make-failure (listof Node))

;; A Result is (anyof Success Failure)
```

> find-path/list

```scheme
;; find-path/list: (listof Node) Node Graph (listof Node) -> Result
(define (find-path/list nbrs dest G visited)
  (cond [(empty? nbrs) (make-failure visited)]
        [(member? (first nbrs) visited)
         (find-path/list (rest nbrs) dest G visited)]
        [else (local [(define result (find-path/acc (first nbrs) dest G visited))]
          (cond [(failure? result) result]
                [(success? result) (make-success (cons orig visited))]))]))
```

*path* was renamed to *result* for clarity.

> find-path/acc

```scheme
;; find-path/acc: Node Node Graph (listof Node) -> Result
(define (find-path/acc orig dest G visited)
  (cond [(symbol=? orig dest) (make-success (list dest))]
        [else (local [(define nbrs (neighbours orig G))
                      (define result (find-path/list nbrs dest G visited))]
                    (cond [(failure? result) result]
                          [(success? result) (success-path result)]))]))
```

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> find-path

```racket
;; find-path: Node Node Graph → (anyof (listof Node) false)
(define (find-path orig dest G)
  (local [[(define result
            (find-path/acc orig dest G empty))]
         [(cond [(success? result) (success-path result)]
                [(failure? result) false]]))
```

> find-path v3 summary

With these changes, find-path runs much faster on the diamond graph.

In future courses we will see how to make find-path even more efficient and how to formalize our analyses.

Knowledge of efficient algorithms, and the data structures that they utilize, is an essential part of being able to deal with large amounts of real-world data.

These topics are studied in CS 240 and CS 341 (for majors) and CS 234 (for non-majors).

Goals of this module

- You should understand directed graphs and their representation in Racket.
- You should be able to write functions which consume graphs and compute desired values.
- You should understand and be able to implement backtracking on explicit and implicit graphs.
- You should understand the problems that the second and third versions of find-path address and how they solve those problems.