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Case study

Problem: Collect bids for a construction project, selecting the lowest bid.

Recipe for user/plan

1. Determine types of data and operations.
2. For each type, choose/modify/create an ADT.
3. Develop pseudocode algorithm using ADT operations.
4. Calculate cost of algorithm with respect to costs of operations.
5. Using information from provider, choose best option.
ADT Priority Queue

Data: (key, element) pairs where

- keys are orderable but not necessarily distinct, and
- elements are any data.

Preconditions: For all $P$ is a priority queue, $Key$ is a key, and $Element$ is an element; for $LOOK_UP_MIN$ and $DELETE_MIN$, $P$ is not empty.

Postconditions: Mutation by $ADD$ (adds pair with key $Key$ and element $Element$) and $DELETE_MIN$ (deletes a pair with minimum key).

<table>
<thead>
<tr>
<th>Name</th>
<th>Returns</th>
</tr>
</thead>
<tbody>
<tr>
<td>$CREATE()$</td>
<td>a new empty priority queue</td>
</tr>
<tr>
<td>$IS_EMPTY(P)$</td>
<td>$True$ if empty, else $False$</td>
</tr>
<tr>
<td>$LOOK_UP_MIN(P)$</td>
<td>pair with minimum key</td>
</tr>
<tr>
<td>$ADD(P, Key, Element)$</td>
<td></td>
</tr>
<tr>
<td>$DELETE_MIN(P)$</td>
<td>pair with minimum key</td>
</tr>
</tbody>
</table>
Contiguous implementations of priority queues

**Contiguous implementation 1**
Data structures:
- Array with all data items stored contiguously, starting at 0
- Variable *First* storing index of first empty slot

**Contiguous implementation 2**
Data structures:
- Array with all data items stored contiguously, starting at 0
- Variable *First* storing index of first empty slot
- Variable *Min* storing index of an item with minimum priority

**Contiguous implementation 3**
Data structures:
- Array with all data items stored contiguously, starting at 0, in decreasing order by key
- Variable *First* storing index of first empty slot
Linked implementations of priority queues

**Linked implementation 1**
Data structures:

- Variable `Head` storing a pointer to a linked list of nodes, each storing a data item and a pointer to the next node in the list

**Linked implementation 2**
Data structures:

- Variable `Head` storing a pointer to a linked list of nodes, each storing a data item and a pointer to the next node in the list
- Variable `Min` storing a pointer to a node storing a data item with minimum priority

**Linked implementation 3**
Data structures:

- Variable `Head` storing a pointer to a linked list of nodes, each storing a data item and a pointer to the next node in the list, in increasing order by key
Data structure: Heap

A binary tree satisfies the **heap-order property** if for each node, the value stored at the node is no greater than that stored in either child.

A **heap** is a complete binary tree that satisfies the heap-order property.

Using a heap to implement the ADT Priority Queue: Store a (key, element) pair at each node, ensuring that the keys satisfy the heap-order property.
Implementing a heap using an array implementation of ADT Binary Tree

Note: Illustrations show keys only, not elements.
Implementing ADT Priority Queue using a heap

**LOOK_UP_MIN(P)**
- Return the data item in the root of tree.
- $\Theta(1)$ to find item in position 0 in the array.

**ADD(P, Key, Element)**
- To preserve completeness, add at next leaf position.
- $\Theta(1)$ to calculate position ($Last + 1$) and update $Last$
- Problem: Heap-order property violated.

**DELETE_MIN(P)**
- To preserve heap-order property, remove the root.
- Problem: What remains is not a tree.
Implementing $ADD(P, Key, Element)$ in a heap

“Bubble up”, fixing heap-order property on path from leaf to root by swapping the values stored in a node and its parent.
Here 18 has just been added.
Implementing $\text{ADD}(P, \text{Key, Element})$ in a heap

“Bubble up”, fixing heap-order property on path from leaf to root by swapping the values stored in a node and its parent.

Here 18 has just been added.
Implementing \textit{ADD}(P, \textit{Key}, \textit{Element}) in a heap

“Bubble up”, fixing heap-order property on path from leaf to root by swapping the values stored in a node and its parent.

Here 18 has just been added.
Augmenting the ADT Binary Tree

We will augment the ADT Binary Tree in order to support:

- Storing of both keys and elements at each node.
- Access to either key or element.

Note: Only keys are ordered using the heap order property.

Modified ADT Binary Tree operations:

- \text{ADD_LEAF}(B, \text{Par}, \text{Side}, \text{Key}, \text{Element})
- \text{SET_VALUES}(B, \text{Node}, \text{Key}, \text{Element})

New operations:

- \text{KEY}(B, \text{Node})
- \text{ELEMENT}(B, \text{Node})
- \text{SIDE}(B, \text{Node}) - produces \text{Left} or \text{Right}
- \text{SWAP_NODE_VALUES}(B, \text{One}, \text{Two}) - exchanges both key and elements in nodes \text{One} and \text{Two}
Heap-specific operations

Each of the operations returns a location of a node (hence an array index):

- \textit{Last Leaf}(B) produces the location of the last leaf
- \textit{Previous Leaf}(B) produces the location of what will be the last leaf if the last leaf is removed
- \textit{Next Leaf}(B) produces the location of the last leaf if a new leaf is added

These operations make use of the fact that a heap is always a complete binary tree.
Constant-time implementations in a heap

We use a variable \textit{Last} to store the index of the array position of the last leaf in the tree.

- \texttt{LAST\_LEAF(B)} returns \textit{Last}
- \texttt{PREVIOUS\_LEAF(B)} returns \textit{Last} - 1
- \texttt{NEXT\_LEAF(B)} returns \textit{Last} + 1

Recall constant-time operations from array implementation of a binary tree: \texttt{ROOT, PARENT, LEFT\_CHILD, RIGHT\_CHILD}

New operations will also all be constant-time operations.
Pseudocode for $ADD(P, Key, Element)$

Last ← $NEXT\_LEAF(B)$
$ADD\_LEAF(B, Parent(B, Last), Side(B, Last), Key, Element)$
$Curr ← Last$
$Par ← PARENT(B, Curr)$

while $Par \neq False$ and $KEY(B, Curr) < KEY(B, Par)$

$SWAP\_NODE\_VALUES(B, Curr, Par)$
$Curr ← Par$
$Par ← PARENT(B, Curr)$
Implementing $\text{DELETE_MIN}(P)$ in a heap

Delete value in root, move value in last leaf to root.

“Bubble down”, fixing heap-order property on path from root to leaf using $\text{SWAP_NODE_VALUES}$.

Be careful to check both children of a node.
Implementing $\text{DELETE}_\text{MIN}(P)$ in a heap

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Implementing $\textit{DELETE\_MIN}(P)$ in a heap

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![Binary Min Heap Diagram]
Implementing $\text{DELETE\_MIN}(P)$ in a heap

Delete value in root, move value in last leaf to root.

“Bubble down”, fixing heap-order property on path from root to leaf using $\text{SWAP\_NODE\_VALUES}$.

Be careful to check both children of a node.
DELETE_MIN algorithm

Ideas used in the pseudocode (to follow):

- Swap the values in the last leaf and the root.
- Delete the last leaf and update the index for Last.
- Starting at the root as the current node, compare the values of the current node and its children.
- If the current node does not have the smallest value, swap its value with the smaller value held in a child and make the child the current node.
- If the current node has only a left child and not a right child, swap its value with the child’s value if the child’s value is smaller.
- Return the minimum value.
DELETE_MIN pseudocode, part 1

Min_Key ← Key(B, Root(B))
Min_Element ← Element(ROOT(B))
SWAP_NODE_VALUES(B, Root(B), Last)
DELETE_NODE(B, Last)
Last ← PREVIOUS_LEAF(B)
Curr ← Root(B)
Left ← LEFT_CHILD(B, Curr)
Right ← RIGHT_CHILD(B, Curr)
Key ← KEY(B, Curr)
Stop ← False
**Delete Min** pseudocode, part 2

while Left ≠ False and not Stop

  Min_Child ← Left

  if Right ≠ False and KEY(B, Right) < KEY(B, Left)

    Min_Child ← Right

  if KEY(B, Min_Child) < Key

    SWAP_NODE_VALUES(B, Curr, Min_Child)

    Curr ← Min_Child

    Left ← LEFT_CHILD(B, Curr)

    Right ← RIGHT_CHILD(B, Curr)

  else

    Stop ← True

return Min_Key, Min_Element
Extracting pairs ordered by key

Goal: Produce the pairs in the priority queue in sorted order by key.

Options for producing sorted pairs:

- Write an algorithm using existing ADT operations.
- Augment the ADT by adding a new operation.

Using existing ADT operations:

- Repeatedly use ADD until all values have been entered.
- Repeatedly use DELETE_MIN.

Analysis:

- $\Theta(n \log n)$ for $n$ ADD operations
- $\Theta(n \log n)$ for $n$ DELETE_MIN operations

Provider view
Can we find a faster way to make a heap out of $n$ elements?
Augmenting ADT Priority Queue

Form heap out of a bunch of (key, element) pairs.

The *HEAPIFY* operation forms a heap out of an array of items.

Idea:

- Place all items into the structure.
- Fix heap-order property from bottom up.
- Observe that leaves are heaps of height 0.
- At phase $i$, form heaps of height at most $i$ from two heaps of height at most $i - 1$. 
**HEAPIFY example, phase 1**
**HEAPIFY** example, phase 2
HEAPIFY example, phase 3
Linear-time $\textsc{Heapify}$ analysis

- Placement into structure takes $\Theta(n)$ time total
- Logarithmic number of phases, in phase $i$ forming at most $n/2^{i+1}$ heaps of height $i$ each
- Cost of making one heap of height $i$ is in $\Theta(i)$, bounded above by some $c_i$
- Total cost of phases is at most $\sum_{i=1}^{\lceil \log n \rceil} c_i \cdot \frac{n}{2^{i+1}} \leq cn\left(\frac{1}{4} + \frac{2}{8} + \frac{3}{16} + \cdots\right)$, which is linear in $n$
- Total cost in $O(n)$
Heapsort:

- Build a heap using \texttt{HEAPIFY}.
- Extract pairs in order using \texttt{DELETE\_MIN} repeatedly.

Analysis on \( n \) elements:

- \( O(n) \) time
- \( n \) iterations, each \( O(\log n) \) time

Total cost: \( O(n \log n) \) time
Module summary

Topics covered:

- Case study: Bids
- ADT Priority Queue
- Contiguous implementations
- Linked implementations
- Data structure: Heap
- Extracting pairs ordered by key
- Sorting using a heap