#### Lecture 24: Review Session & AMA

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## Overview

- Review Session
  - Divide-and-Conquer
  - Greedy
  - Dynamic Programming
  - Graph Algorithms
  - Max-Flow Min-Cut
  - Reductions
  - Intractability
- Ask me Anything
- Acknowledgements

- Structure of divide-and-conquer:
  - Divide: given instance *I*, construct smaller instances *I*<sub>1</sub>,..., *I*<sub>a</sub> (subproblems)

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- **③ Combine:** solutions  $S_1, \ldots, S_a \mapsto$  solution S to instance I
- "Recursion for running time:"

 $T(I) = T(I_1) + \cdots + T(I_a) + \text{ time to combine}$ 

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# Greedy Algorithms

- Greedy strategy based on following principles:
  - choose a "progress measure"
  - Preprocess input accordingly
  - Imake next decision based on what is best given current partial solution
  - Main idea: must show that the greedy solution is always no worse than any other optimal solution!

Usually can prove this by begin able to "transform" any optimal solution into the greedy one without losing anything.

#### **Exchange Argument**

Optimal Substructure: a problem has optimal substructure if any optimal solution contains optimal solutions to subproblems.

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#### DP template

- identify small set of subproblems
- 2 devise proper recursion
- Show how bottom-up approach correctly compute the subproblems

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- BFS
  - Finds shortest paths
  - ② Can be used to detect graph is bipartite
  - Shortest paths encoded in the BFS tree
  - On-tree edges in adjacent layers

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DFS

- Parenthesis lemma: start and finish time intervals are either disjoint, or one contains the other
- Inon-tree edges (in DFS tree) must be back edges
- O checks for cut vertices or cut edges

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- Any directed graph is a DAG of SCCs (strongly connected components)
- Linear time algorithm to find all SCCs!

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- All of the above can be assumed to run in  $O(m \log n)$  time.

#### Shortest Paths

- Single-source, all weights non-negative: Dijkstra
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- All-pairs shortest-paths (arbitrary weights, no negative cycles)

#### Floyd-Warshall

- Subproblems: D[u, v, k] := shortest  $u \to v$  path using only  $\{1, \dots, k\}$  as intermediate vertices
- Runtime  $O(n^3)$

Let G(V, E, c) be an undirected graph, with capacity (weight) function  $C: E \to \mathbb{R}_{\geq 0}$ , two special vertices  $s, t \in V$ 

- Capacity:  $f(e) \le c(e)$  for all  $e \in E$
- 2 Conservation:  $f_{in}(u) = f_{out}(u)$  for all  $u \in V \setminus \{s, t\}$
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- Ford-Fulkerson algorithm: keep finding  $s \rightarrow t$  paths in residual graph, when there is none, found a max-flow and a min-cut

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- *Turing reductions* (a.k.a. Cook reductions)
  - $A \leq_p^T B \Leftrightarrow$  there is a poly-time algorithm  $M^B$  with oracle access to B such that  $M^B$  solves A.
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- Karp reductions (a.k.a. polynomial transformations)
  - $A \leq_p B \Leftrightarrow$  there is a poly-time computable function  $f : A \to B$  such that
    - x is a YES instance of  $A \Leftrightarrow f(x)$  is YES instance of B

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  - there is an NP-complete problem A such that

 $A \leq_{p} B$ 

**Notation:**  $A \leq_p B$  is the same as I have used as  $A \leq_m B$ . These are polynomial transformations (a.k.a. Karp reductions).

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- Example:
  - HITTINGSET
    - Input: collection of sets  $S_1, \ldots, S_m \subset [n]$ , integer  $k \in \mathbb{N}$
    - Is there a collection of k sets S<sub>i</sub> which contain all elements of [n]?

• A problem *B* is NP-hard if there is an NP-complete problem *A* such that

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• A real proof can be found here

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## AMA

# Acknowledgement

Based on

• Entire course :)

# References I

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