Virtual and Physical Addresses

- Physical addresses are provided directly by the machine.
  - one physical address space per machine
  - the size of a physical address determines the maximum amount of addressable physical memory
- Virtual addresses (or logical addresses) are addresses provided by the OS to processes.
  - one virtual address space *per process*
- Programs use virtual addresses. As a program runs, the hardware (with help from the operating system) converts each virtual address to a physical address.
- The conversion of a virtual address to a physical address is called *address translation*.

On the MIPS, virtual addresses and physical addresses are 32 bits long. This limits the size of virtual and physical address spaces.

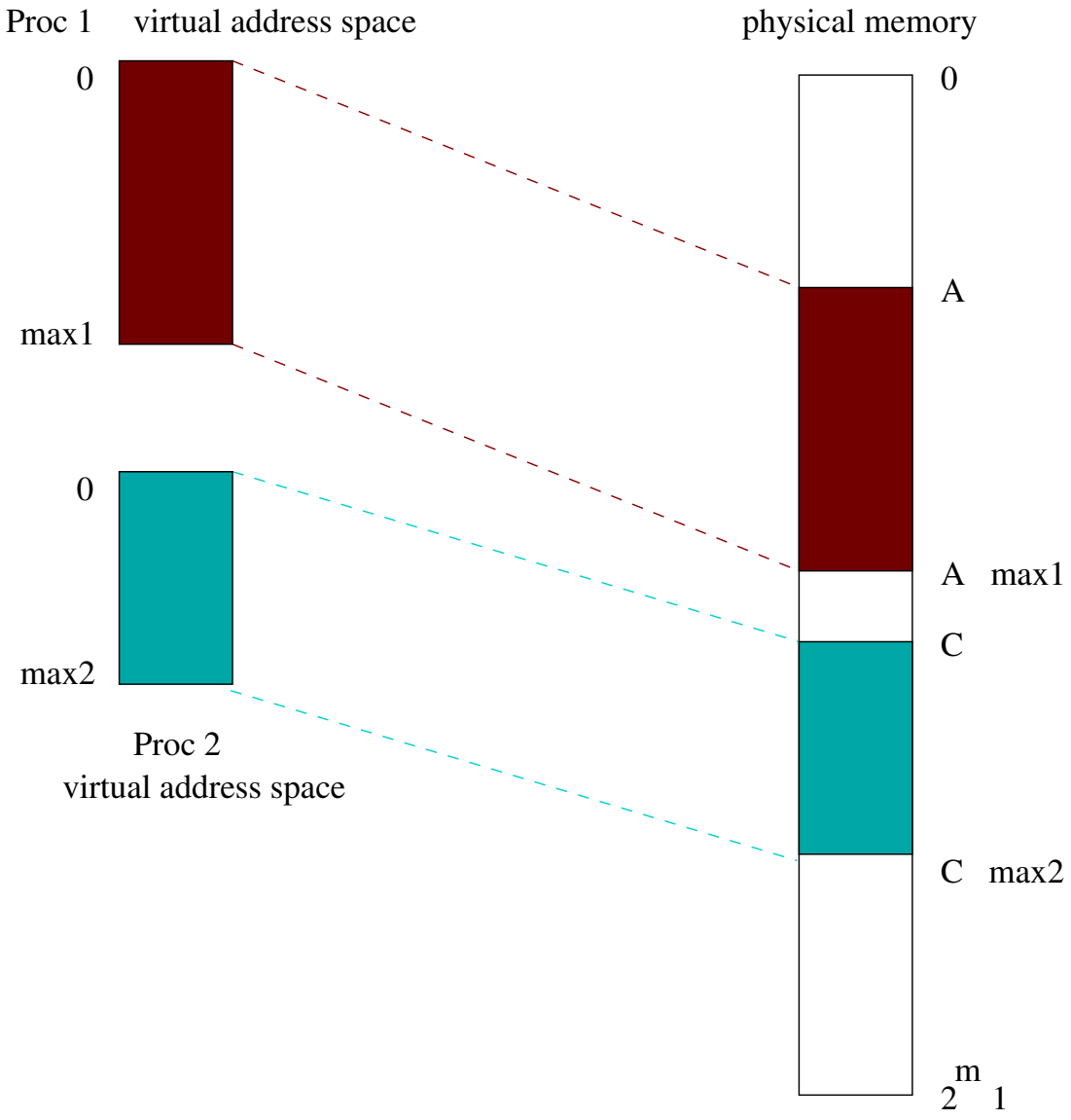
Simple Address Translation: Dynamic Relocation

- hardware provides a *memory management unit (MMU)* which includes a *relocation register* and a *limit register* (or *bound register*).
- to translate a virtual address to a physical address, the MMU:
  - checks whether the virtual address is larger than the limit in the limit register
  - if it is, the MMU raises an *exception*
  - otherwise, the MMU adds the base address (stored in the relocation register) to the virtual address to produce the physical address
- The OS maintains a separate base address and limit for each process, and ensures that the relocation and limit registers in the MMU always contain the base address and limit of the currently-running process.
- To ensure this, the OS must normally change the values in the MMU's registers during each context switch.

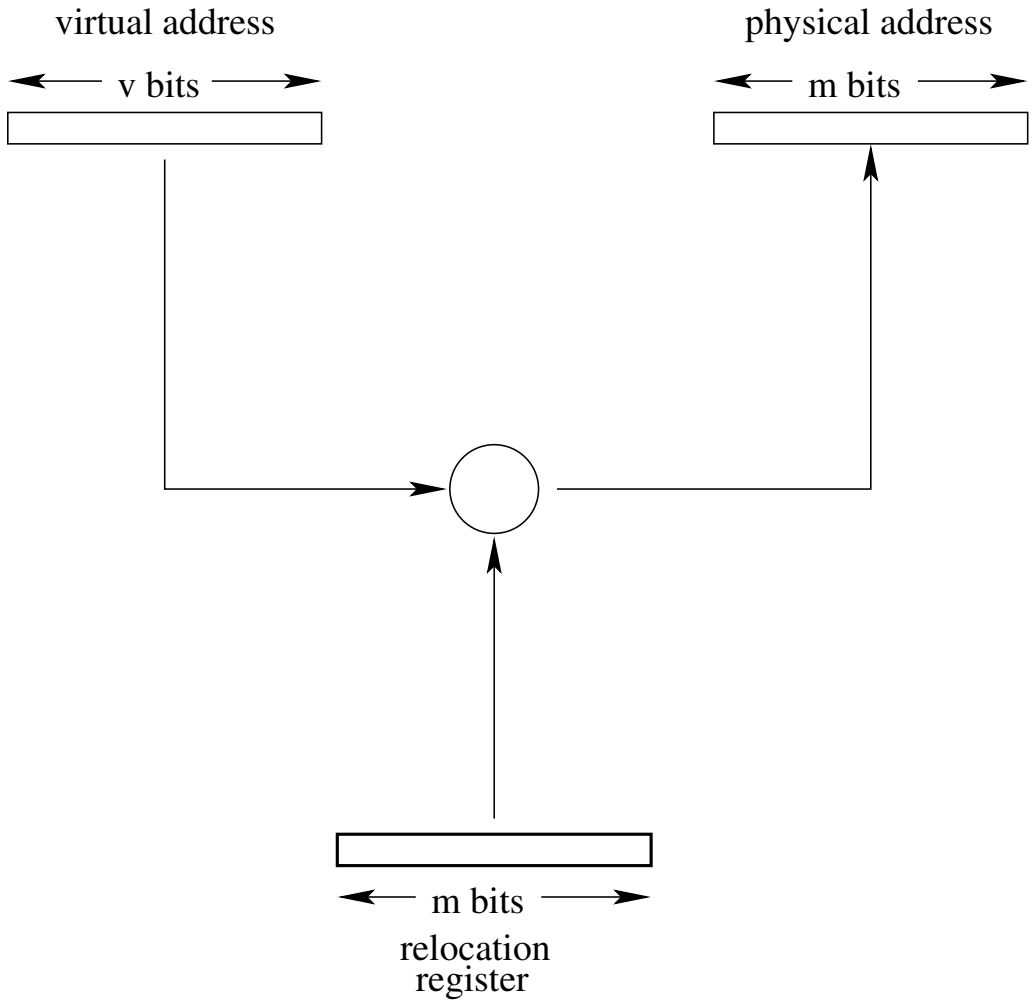
Properties of Dynamic Relocation

- each virtual address space corresponds to a *contiguous range of physical addresses*
- the OS is responsible for deciding *where* each virtual address space should map to in physical memory
  - the OS must track which parts of physical memory are in use, and which parts are free
  - since different address spaces may have different sizes, the OS must allocate/deallocate variable-sized chunks of physical memory
  - this creates the potential for *external fragmentation* of physical memory: wasted, unallocated space
- the MMU is responsible for performing all address translations, using base and limit information provided to it by the the OS

Dynamic Relocation: Address Space Diagram



Dynamic Relocation Mechanism

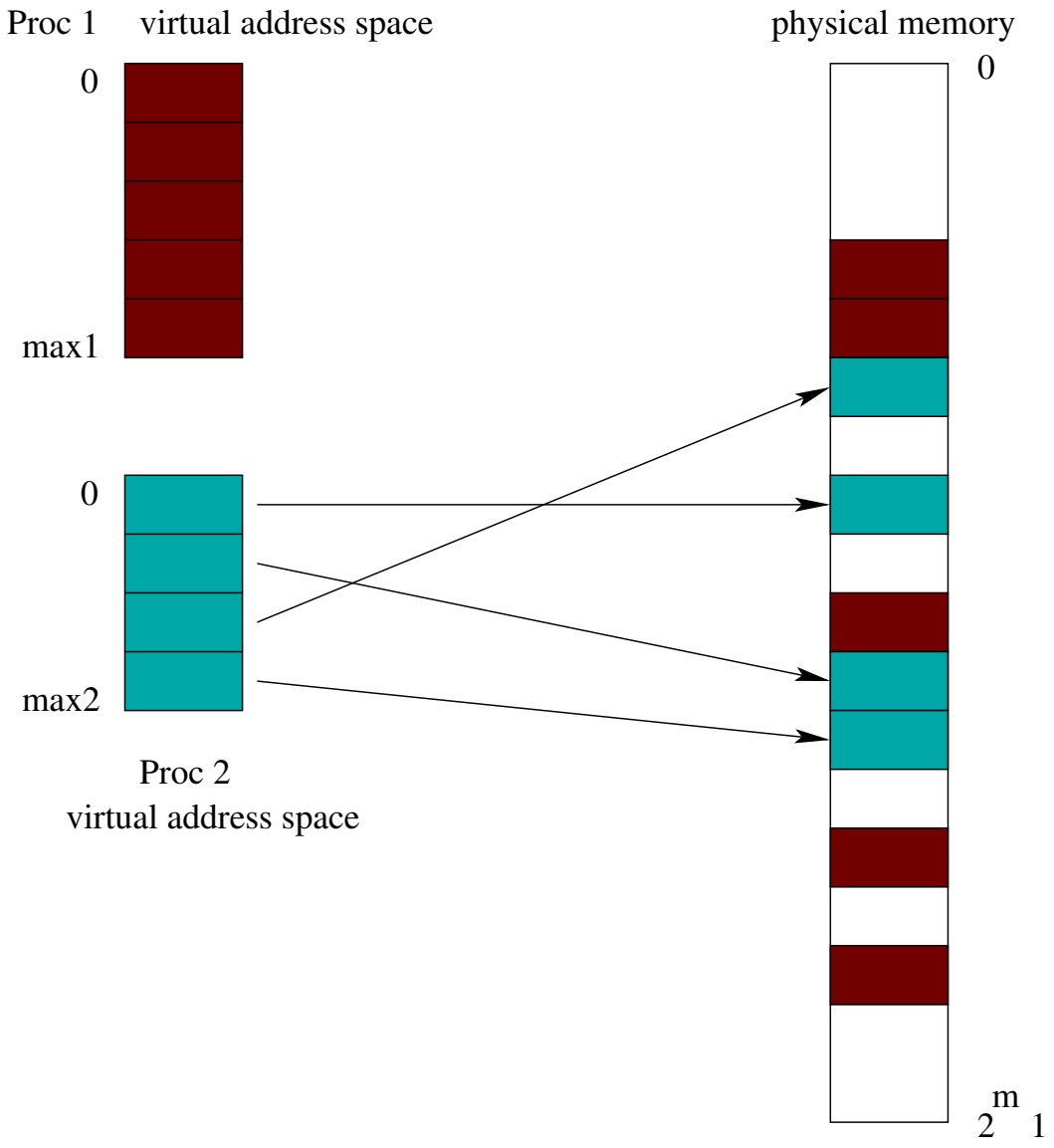


This diagram shows only the address translation, not the limit check.

Address Translation: Paging

- Each virtual address space is divided into fixed-size chunks called *pages*
- The physical address space is divided into *frames*. Frame size matches page size.
- OS maintains a *page table* for each process. Page table specifies the frame in which each of the process's pages is located.
- At run time, MMU translates virtual addresses to physical using the page table of the running process.

Address Space Diagram for Paging



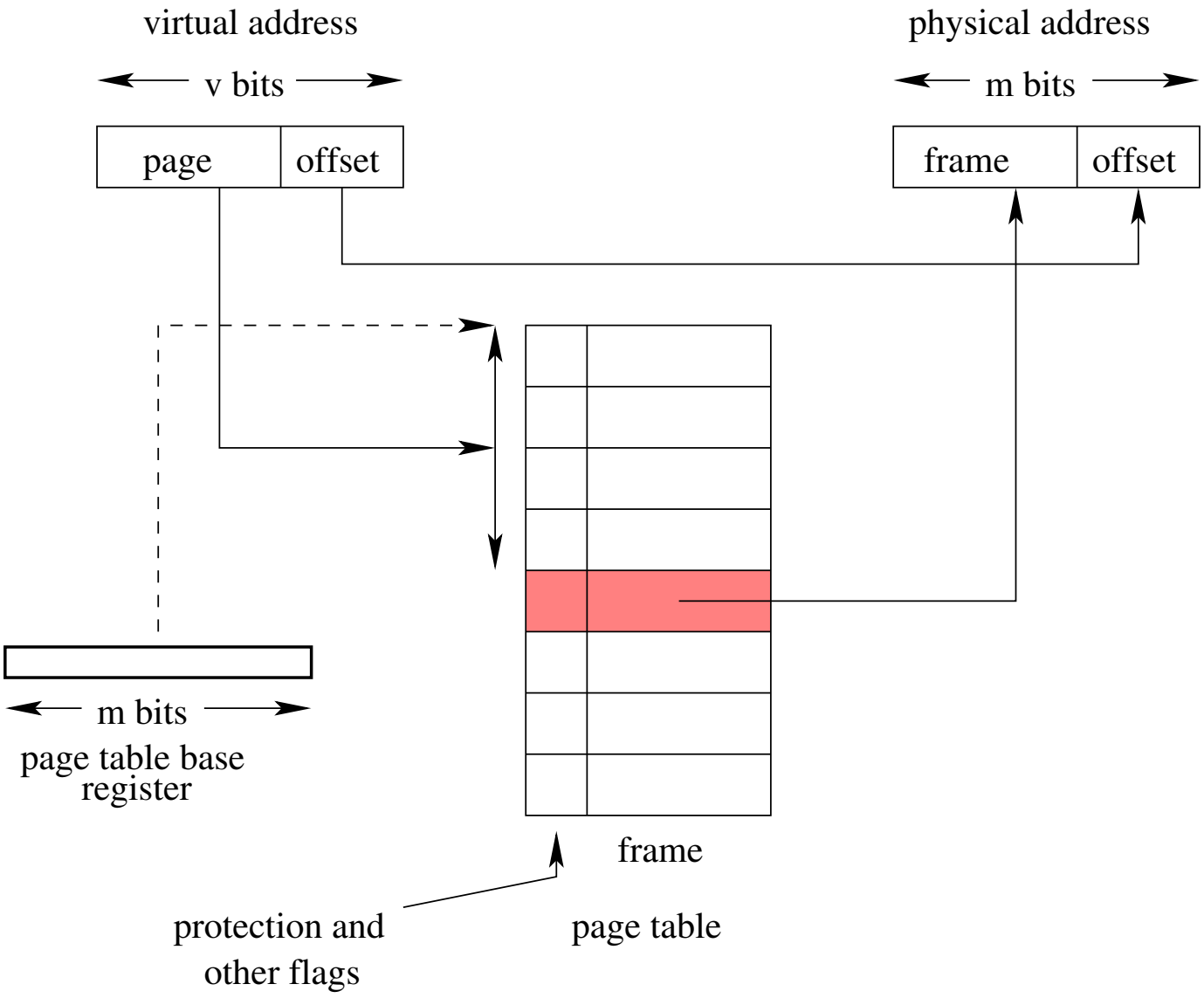
Properties of Paging

- OS is responsible for deciding which frame will hold each page
  - simple physical memory management
  - potential for *internal fragmentation* of physical memory: wasted, allocated space
  - virtual address space need not be physically contiguous in physical space after translation.
- MMU is responsible for performing all address translations using the page table that is created and maintained by the OS.
- The OS must normally change the values in the MMU registers on each context switch, so that they refer to the page table of the currently-running process.

How the MMU Translates Virtual Addresses

- The MMU includes a *page table base register* and a *page table length register*.
  - the base register contains the (physical) address of the first page table entry for the currently-running process
  - the length register contains the number of entries in the page table of the currently running process.
- To translate a virtual address, the MMU:
  - determines the *page number* and *offset* of the virtual address
  - checks whether the page number is larger than the value in the page table length register
  - if it is, the MMU raises an exception
  - otherwise, the MMU uses the page table to determine the *frame number* of the frame that holds the virtual page, and combines the frame number and offset to determine the physical address

Paging Mechanism



Page Table Entries

- the primary payload of each page table entry (PTE) is a frame number
- PTEs typically contain other information as well, such as
  - information provided by the kernel to control address translation by the MMU, such as:
    - valid bit: is the process permitted to use this part of the address space?
    - present bit: is this page mapped into physical memory (useful with page replacement, to be discussed later)
    - protection bits: to be discussed
  - information provided by the MMU to help the kernel manage address spaces, such as:
    - reference (use) bit: has the process used this page recently?
    - dirty bit: has the process changed the contents of this page?

Validity and Protection

- during address translation, the MMU checks that the page being used by the process has a *valid* page table entry
  - typically, each PTE contains a *valid bit*
  - invalid PTEs indicate pages that the process is not permitted to use
- the MMU may also enforce other protection rules, for example
  - each PTE may contain a *read-only* bit that indicates whether the corresponding page is read-only, or can be modified by the process
- if a process attempts to access an invalid page, or violates a protection rule, the MMU raises an exception, which is handled by the kernel

---

The kernel controls which pages are valid and which are protected by setting the contents of PTEs and/or MMU registers.

Summary: Roles of the Kernel and the MMU

- Kernel:
  - manage MMU state on address space switches (context switch from thread in one process to thread in a different process)
  - create and manage page tables
  - manage (allocate/deallocate) physical memory
  - handle exceptions raised by the MMU
- MMU (hardware):
  - translate virtual addresses to physical addresses
  - check for and raise exceptions when necessary

Speed of Address Translation

- Execution of each machine instruction may involve one, two or more memory operations
  - one to fetch instruction
  - one or more for instruction operands
- Address translation through a page table adds one extra memory operation (for page table entry lookup) for each memory operation performed during instruction execution
  - Simple address translation through a page table can cut instruction execution rate in half.
  - More complex translation schemes (e.g., multi-level paging) are even more expensive.
- Solution: include a Translation Lookaside Buffer (TLB) in the MMU
  - TLB is a fast, fully associative address translation cache
  - TLB hit avoids page table lookup

TLB

- Each entry in the TLB contains a (page number, frame number) pair.
- If address translation can be accomplished using a TLB entry, access to the page table is avoided.
  - This is called a *TLB hit*.
- Otherwise, translate through the page table.
  - This is called a *TLB miss*.
- TLB lookup is much faster than a memory access. TLB is an associative memory - page numbers of all entries are checked simultaneously for a match. However, the TLB is typically small (typically hundreds, e.g. 128, or 256 entries).
- If the MMU cannot distinguish TLB entries from different address spaces, then the kernel must clear or invalidate the TLB on each context switch. (Why?)

TLB Management

- An TLB may be *hardware-controlled* or *software-controlled*
- In a hardware-controlled TLB, when there is a TLB miss:
  - The MMU (hardware) finds the frame number by performing a page table lookup, translates the virtual address, and adds the transalation (page number, frame number pair) to the TLB.
  - If the TLB is full, the MMU evicts an entry to make room for the new one.
- In a software-controlled TLB, when there is a TLB miss:
  - the MMU simply causes an exception, which triggers the kernel exception handler to run
  - the kernel must determine the correct page-to-frame mapping and load the mapping into the TLB (evicting an entry if the TLB is full), before returning from the exception
  - after the exception handler runs, the MMU retries the instruction that caused the exception.

The MIPS R3000 TLB

- The MIPS has a software-controlled TLB that can hold 64 entries.
- Each TLB entry includes a virtual page number, a physical frame number, an address space identifier (not used by OS/161), and several flags (valid, read-only).
- OS/161 provides low-level functions for managing the TLB:

  TLB_Write: modify a specified TLB entry

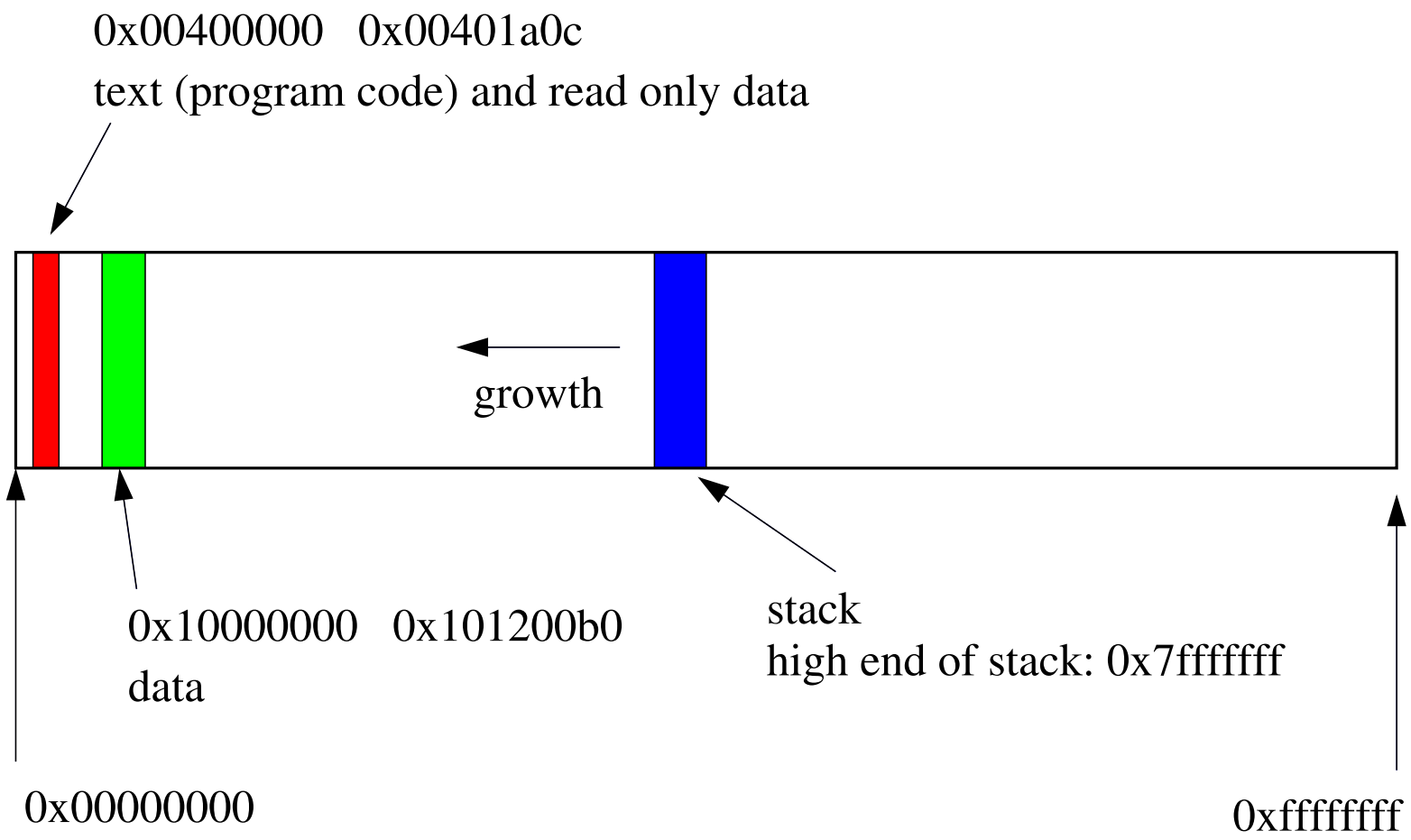
  TLB_Read: read a specified TLB entry

  TLB_Probe: look for a page number in the TLB

- If the MMU cannot translate a virtual address using the TLB it raises an exception, which must be handled by OS/161.

See `kern/arch/mips/include/tlb.h`

What is in a Virtual Address Space?



This diagram illustrates the layout of the virtual address space for the OS/161 test application `user/testbin/sort`

Address Translation In OS/161: dumbvm

- OS/161 starts with a very simple virtual memory implementation
- virtual address spaces are described by `addrspace` objects, which record the mappings from virtual to physical addresses

```
struct addrspace {
#if OPT_DUMBVM
  vaddr_t as_vbase1; /* base virtual address of code segment */
  paddr_t as_pbase1; /* base physical address of code segment */
  size_t as_npages1; /* size (in pages) of code segment */
  vaddr_t as_vbase2; /* base virtual address of data segment */
  paddr_t as_pbase2; /* base physical address of data segment */
  size_t as_npages2; /* size (in pages) of data segment */
  paddr_t as_stackpbase; /* base physical address of stack */
#else
  /* Put stuff here for your VM system */
#endif
};
```

- Notice that each segment must be mapped contiguously into physical memory.

Address Translation Under `dumbvm`

- the MIPS MMU tries to translate each virtual address using the entries in the TLB
- If there is no valid entry for the page the MMU is trying to translate, the MMU generates a TLB fault (called an *address exception*)
- The `vm_fault` function (see `kern/arch/mips/vm/dumbvm.c`) handles this exception for the OS/161 kernel. It uses information from the current process' `addrspace` to construct and load a TLB entry for the page.
- On return from exception, the MIPS retries the instruction that caused the exception. This time, it may succeed.

`vm_fault` is not very sophisticated. If the TLB fills up, OS/161 will crash!

Initializing an Address Space

- When the kernel creates a process to run a particular program, it must create an address space for the process, and load the program's code and data into that address space

---

OS/161 *pre-loads* the address space before the program runs. Many other OS load pages *on demand*. (Why?)

- A program's code and data is described in an *executable file*, which is created when the program is compiled and linked
- OS/161 (and some other operating systems) expect executable files to be in ELF (**E**xecutable and **L**inking **F**ormat) format
- The OS/161 `execv` system call re-initializes the address space of a process

```
int execv(const char *program, char **args)
```

- The `program` parameter of the `execv` system call should be the name of the ELF executable file for the program that is to be loaded into the address space.

ELF Files

- ELF files contain address space segment descriptions, which are useful to the kernel when it is loading a new address space
- the ELF file identifies the (virtual) address of the program's first instruction
- the ELF file also contains lots of other information (e.g., section descriptors, symbol tables) that is useful to compilers, linkers, debuggers, loaders and other tools used to build programs

Address Space Segments in ELF Files

- The ELF file contains a header describing the segments and segment *images*.
- Each ELF segment describes a contiguous region of the virtual address space.
- The header includes an entry for each segment which describes:
  - the virtual address of the start of the segment
  - the length of the segment in the virtual address space
  - the location of the start of the segment image in the ELF file (if present)
  - the length of the segment image in the ELF file (if present)
- the image is an exact copy of the binary data that should be loaded into the specified portion of the virtual address space
- the image may be smaller than the address space segment, in which case the rest of the address space segment is expected to be zero-filled

---

To initialize an address space, the OS/161 kernel copies segment images from the ELF file to the specifed portions of the virtual address space.

ELF Files and OS/161

- OS/161's `dumbvm` implementation assumes that an ELF file contains two segments:
  - a *text segment*, containing the program code and any read-only data
  - a *data segment*, containing any other global program data
- the ELF file does not describe the stack (why not?)
- `dumbvm` creates a *stack segment* for each process. It is 12 pages long, ending at virtual address `0x7fffffff`

Look at `kern/syscall/loadelf.c` to see how OS/161 loads segments from ELF files

ELF Sections and Segments

- In the ELF file, a program's code and data are grouped together into *sections*, based on their properties. Some sections:

  .text: program code

  .rodata: read-only global data

  .data: initialized global data

  .bss: uninitialized global data (Block Started by Symbol)

  .sbss: small uninitialized global data

- not all of these sections are present in every ELF file
- normally
  - the `.text` and `.rodata` sections together form the text segment
  - the `.data`, `.bss` and `.sbss` sections together form the data segement
- space for *local* program variables is allocated on the stack when the program runs

The `user/uw-testbin/segments.c` Example Program (1 of 2)

```
#include <unistd.h>

#define N   (200)

int x = 0xdeadbeef;
int t1;
int t2;
int t3;
int array[4096];
char const *str = "Hello World\n";
const int z = 0xabcddcba;

struct example {
  int ypos;
  int xpos;
};
```

The `user/uw-testbin/segments.c` Example Program (2 of 2)

```
int
main()
{
  int count = 0;
  const int value = 1;
  t1 = N;
  t2 = 2;
  count = x + t1;
  t2 = z + t2 + value;

  reboot(RB_POWEROFF);
  return 0; /* avoid compiler warnings */
}
```

ELF Sections for the Example Program

```
Section Headers:
[Nr] Name              Type            Addr     Off    Size   Flg
[ 0]                   NULL            00000000 000000 000000
[ 1] .text             PROGBITS        00400000 010000 000200  AX
[ 2] .rodata           PROGBITS        00400200 010200 000020   A
[ 3] .reginfo          MIPS_REGINFO    00400220 010220 000018   A
[ 4] .data             PROGBITS        10000000 020000 000010  WA
[ 5] .sbss             NOBITS          10000010 020010 000014 WAp
[ 6] .bss              NOBITS          10000030 020010 004000  WA
...
Flags: W (write), A (alloc), X (execute), p (processor specific)

## Size = number of bytes (e.g., .text is 0x200 = 512 bytes
## Off  = offset into the ELF file
## Addr = virtual address
```

The `cs350-readelf` program can be used to inspect OS/161 MIPS ELF files: `cs350-readelf -a segments`

ELF Segments for the Example Program

```
Program Headers:
Type    Offset   VirtAddr   PhysAddr   FileSiz MemSiz  Flg Align
REGINFO 0x010220 0x00400220 0x00400220 0x00018 0x00018 R   0x4
LOAD    0x010000 0x00400000 0x00400000 0x00238 0x00238 R E 0x10000
LOAD    0x020000 0x10000000 0x10000000 0x00010 0x04030 RW  0x10000
```

- segment info, like section info, can be inspected using the `cs350-readelf` program
- the REGINFO section is not used
- the first LOAD segment includes the .text and .rodata sections
- the second LOAD segment includes .data, .sbss, and .bss

Contents of the Example Program's `.text` Section

```
Contents of section .text:
 400000 3c1c1001 279c8000 2408fff8 03a8e824  <...'...$......$
...
## Decoding 3c1c1001 to determine instruction
## 0x3c1c1001 = binary 11110000011100000100000000001
## 0011 1100 0001 1100 0001 0000 0000 0001
## instr  | rs    | rt    |   immediate
## 6 bits | 5 bits| 5 bits|   16 bits
## 001111 | 00000 | 11100 |  0001 0000 0000 0001
## LUI    | 0     | reg 28|   0x1001
## LUI    | unused| reg 28|   0x1001
## Load upper immediate into rt (register target)
## lui gp, 0x1001
```

The `cs350-objdump` program can be used to inspect OS/161 MIPS ELF file section contents: `cs350-objdump -s segments`

Contents of the Example Program's `.rodata` Section

```
Contents of section .rodata:
 400200 abcddcba 00000000 00000000 00000000  ................
 400210 48656c6c 6f20576f 726c640a 00000000  Hello World.....
...
## const int z = 0xabcddcba
## If compiler doesn't prevent z from being written,
##    then the hardware could.
## 0x48 = 'H' 0x65 = 'e' 0x0a = '\n' 0x00 = '\0'
```

The `.rodata` section contains the "Hello World" string literal and the constant integer variable `z`.

Contents of the Example Program's `.data` Section

```
Contents of section .data:
 10000000 deadbeef 00400210 00000000 00000000  .....@.........
...
## Size = 0x10 bytes = 16 bytes (padding for alignment)
## int x = deadbeef (4 bytes)
## char const *str = "Hello World\n"; (4 bytes)
## address of str = 0x10000004
## value stored in str = 0x00400210.
## NOTE: this is the address of the start
## of the string literal in the .rodata section
```

The `.data` section contains the initialized global variables `str` and `x`.

Contents of the Example Program's `.bss` and `.sbss` Sections

```
...
10000000 D x
10000004 D str
10000010 S t3        ## S indicates sbss section
10000014 S t2
10000018 S t1
1000001c S errno
10000020 S __argv
10000030 B array     ## B indicates bss section
10004030 A _end
10008000 A _gp
```

The `t1`, `t2`, and `t3` variables are in the `.sbss` section. The `array` variable is in the `.bss` section. There are no values for these variables in the ELF file, as they are uninitialized. The `cs350-nm` program can be used to inspect symbols defined in ELF files: `cs350-nm -n <filename>`, in this case `cs350-nm -n segments`.

An Address Space for the Kernel

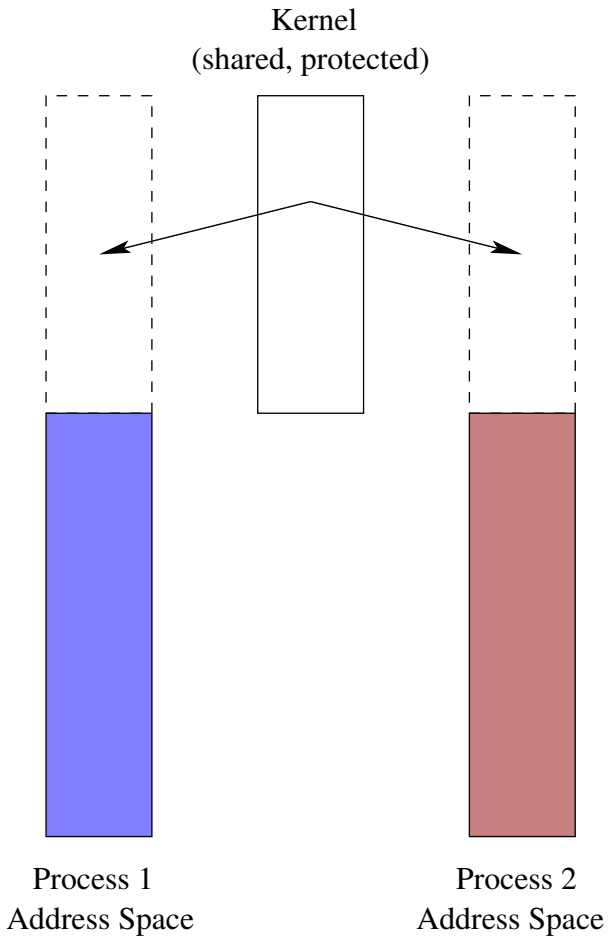
- Each process has its own address space. What about the kernel?
- Three possibilities:

  Kernel in physical space: disable address translation in privileged system execution mode, enable it in unprivileged mode

  Kernel in separate virtual address space: need a way to change address translation (e.g., switch page tables) when moving between privileged and unprivileged code

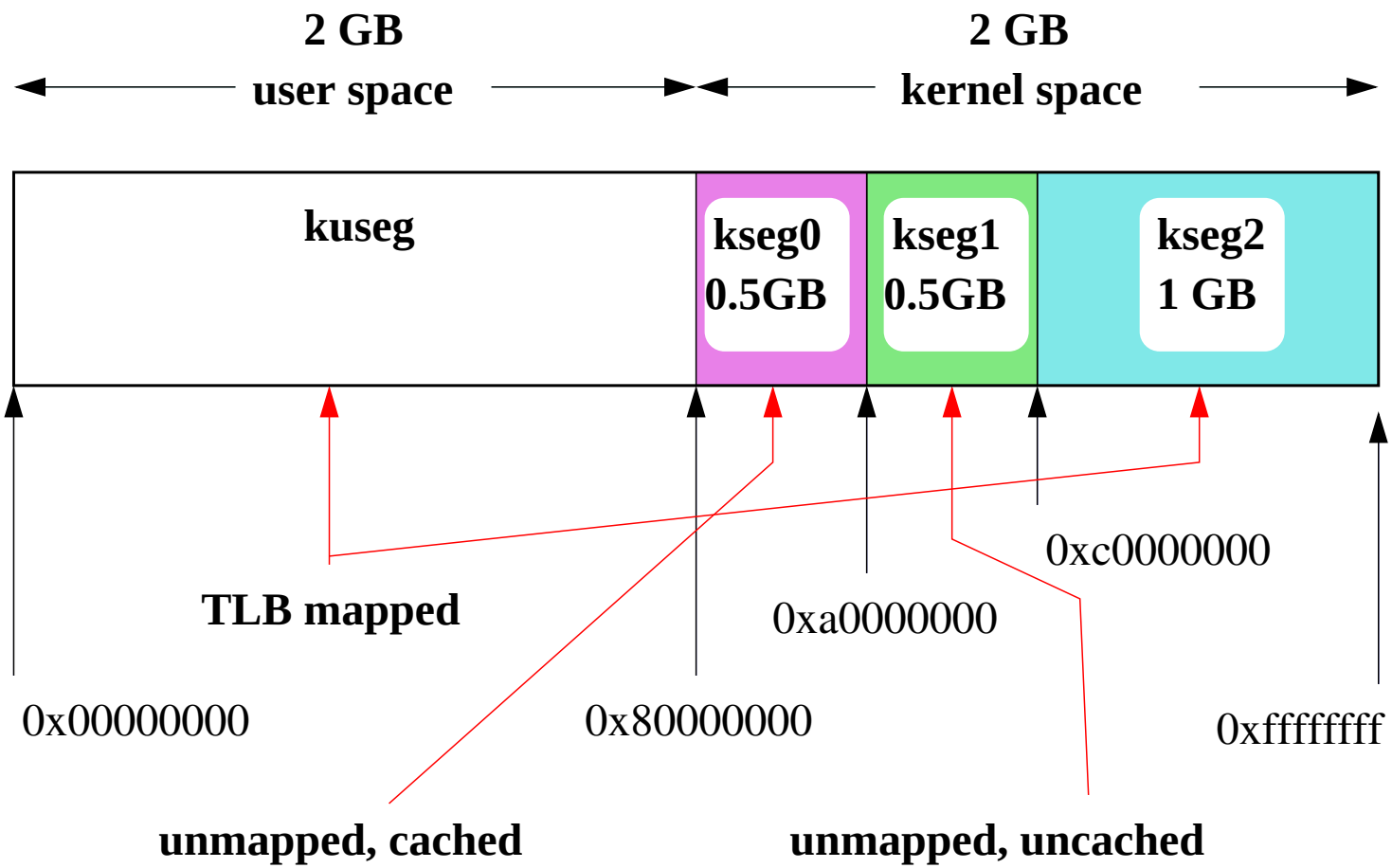
  Kernel mapped into portion of address space of *every process*: OS/161, Linux, and other operating systems use this approach
  - memory protection mechanism is used to isolate the kernel from applications
  - one advantage of this approach: application virtual addresses (e.g., system call parameters) are easy for the kernel to use

The Kernel in Process' Address Spaces



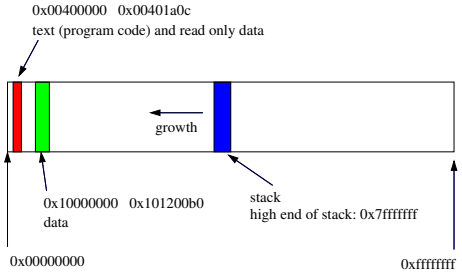
Attempts to access kernel code/data in user mode result in memory protection exceptions, not invalid address exceptions.

Address Translation on the MIPS R3000



In OS/161, user programs live in kuseg, kernel code and data structures live in kseg0, devices are accessed through kseg1, and kseg2 is not used.

The Problem of Sparse Address Spaces



- Consider the page table for `user/testbin/sort`, assuming a 4 Kbyte page:
  - need 2^{19} page table entries (PTEs) to cover the bottom half of the virtual address space (2GB).
  - the text segment occupies 2 pages, the data segment occupies 289 pages, and OS/161 sets the initial stack size to 12 pages, so there are only 303 *valid* pages (of 2^{19}).
- If dynamic relocation is used, the kernel will need to map a 2GB address space contiguously into physical memory, even though only a tiny fraction of that address space is actually used by the program.
- If paging is used, the kernel will need to create a page table with 2^{19} PTEs, almost all of which are marked as not valid.

Handling Sparse Address Spaces

- Use dynamic relocation, but provide separate base and length for each valid segment of the address space. Do not map the rest of the address space.
  - OS/161 `dumbvm` uses a simple variant of this idea, which depends on having a software-managed TLB.
  - A more general approach is *segmentation*.
- A second approach is to use *multi-level paging*
  - replace the single large linear page table with a hierarchy of smaller page tables
  - a sparse address space can be mapped by a sparse tree hierarchy
  - easier to manage several smaller page tables than one large one (remember: each page table must be continguous in physical memory!)

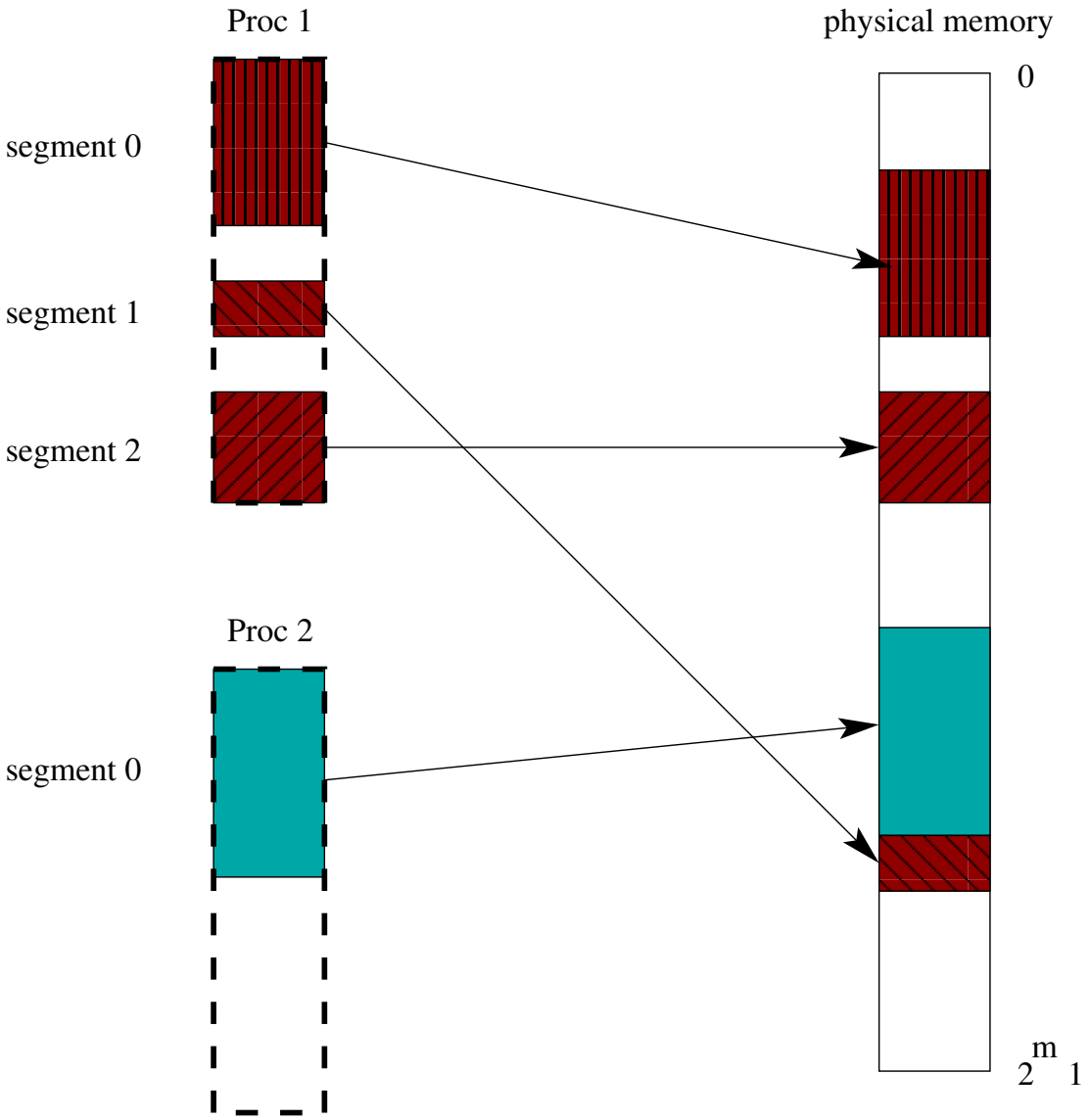
Segmentation

- Often, programs (like `sort`) need several virtual address segments, e.g, for code, data, and stack.
- With segmentation, a virtual address can be thought of as having two parts:

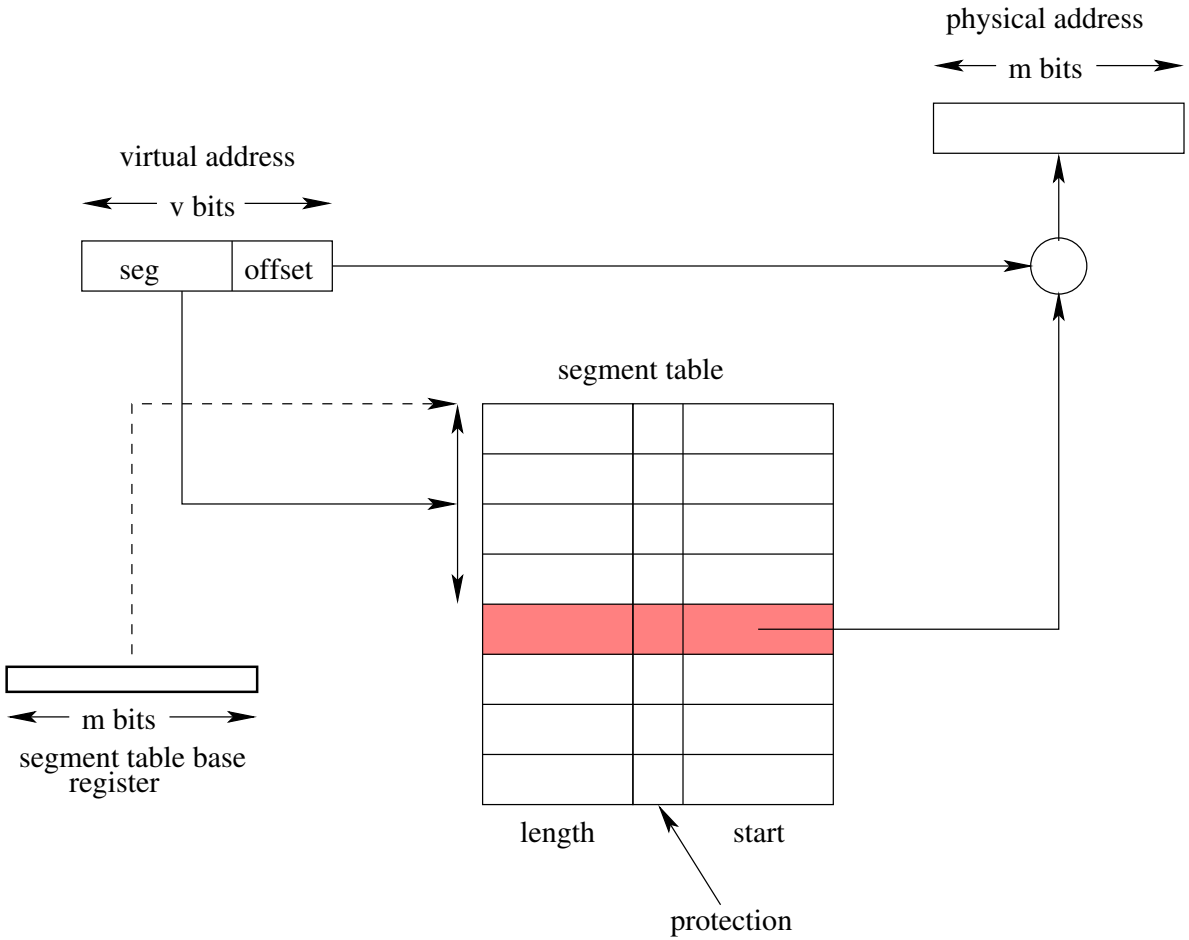
  (segment ID, address within segment)

- Each segment also has a length.

Segmented Address Space Diagram



Mechanism for Translating Segmented Addresses



This translation mechanism requires physically contiguous allocation of segments.

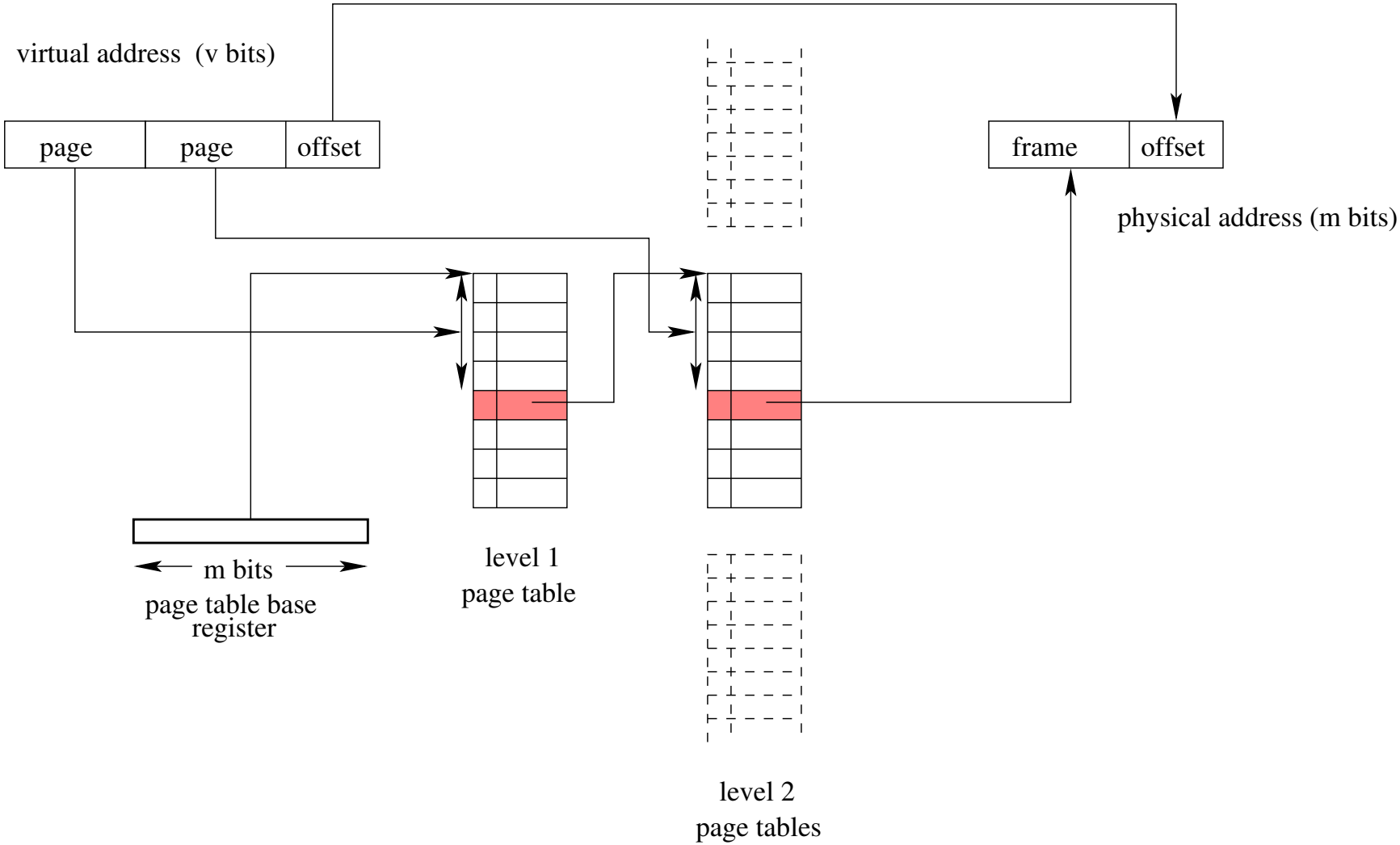
Handling Sparse Paged Virtual Address Spaces

- Large paged virtual address spaces require large page tables.
- example: 2^{48} byte virtual address space, 8 Kbyte (2^{13} byte) pages, 4 byte page table entries means

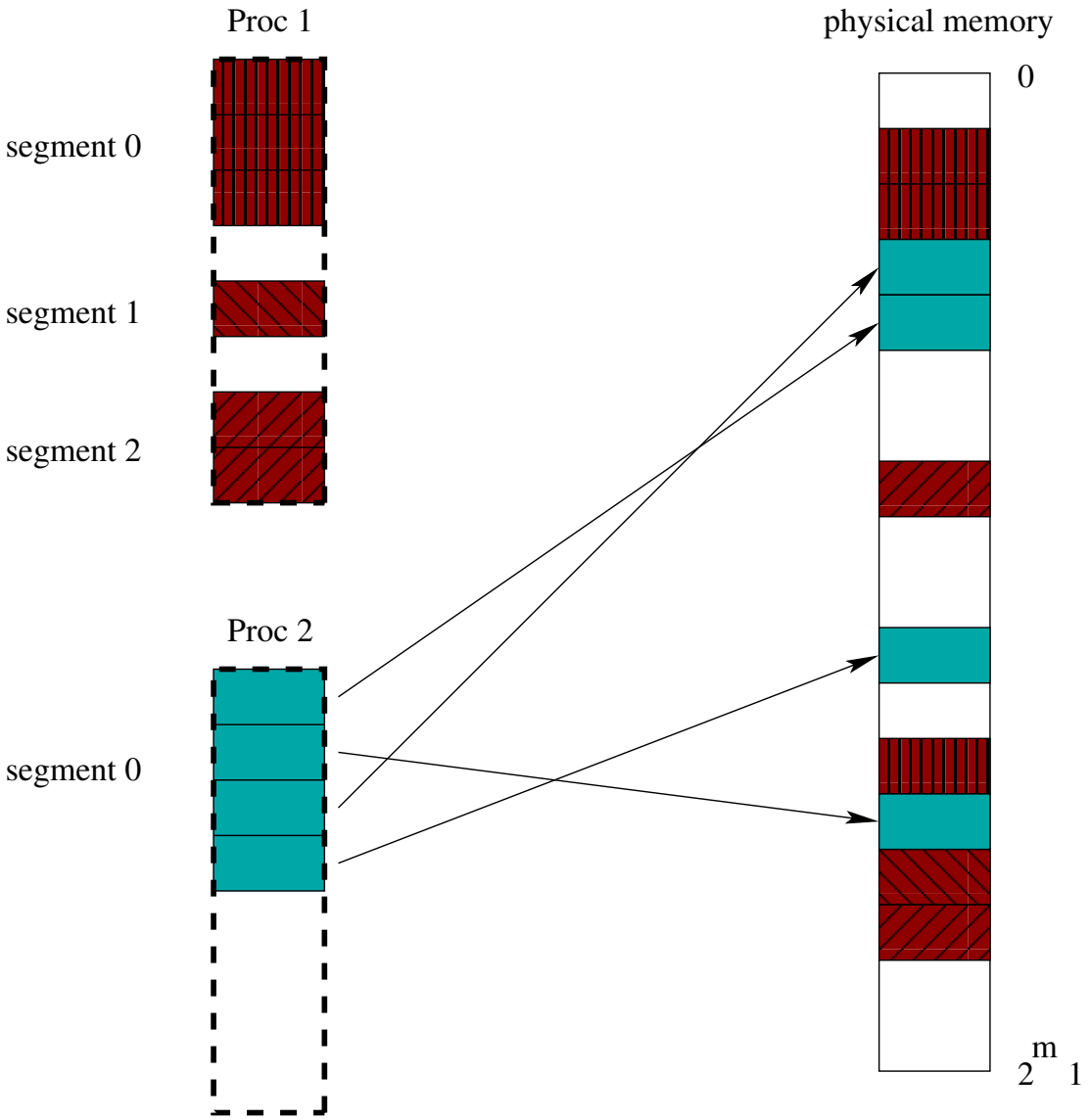
$$\frac{2^{48}}{2^{13}}2^2 = 2^{37} \text{ bytes per page table}$$

- page tables for large address spaces may be very large, and
  - they must be in memory, and
  - they must be physically contiguous

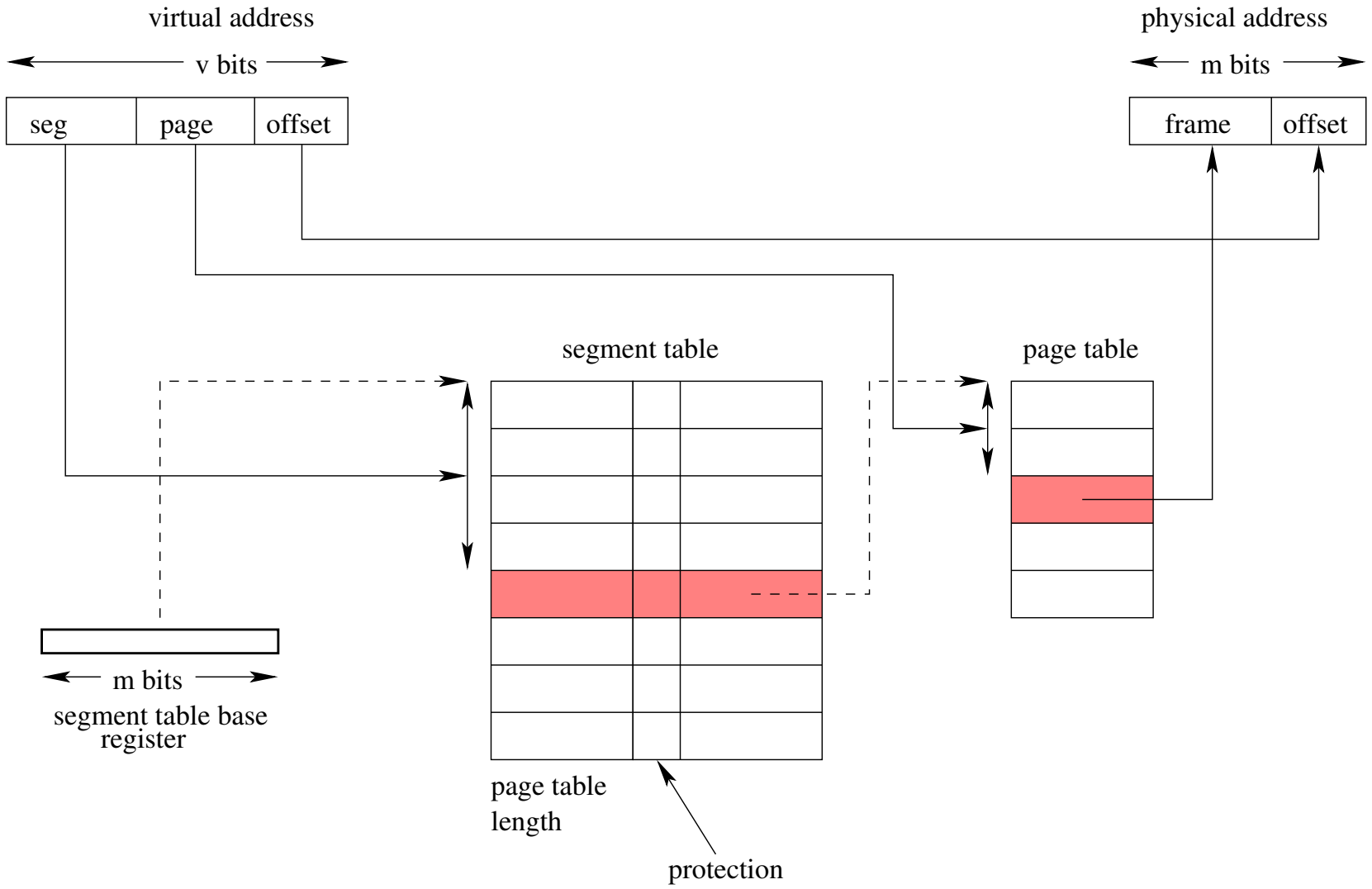
Two-Level Paging



Combining Segmentation and Paging



Combining Segmentation and Paging: Translation Mechanism



Exploiting Secondary Storage

Goals:

- Allow virtual address spaces that are larger than the physical address space.
- Allow greater multiprogramming levels by using less of the available (primary) memory for each process.

Method:

- Allow pages (or segments) from the virtual address space to be stored in secondary storage, e.g., on disks, as well as primary memory.
- Move pages (or segments) between secondary storage and primary memory so that they are in primary memory when they are needed.

Paging Policies

When to Page?:

Demand paging brings pages into memory when they are used. Alternatively, the OS can attempt to guess which pages will be used, and *prefetch* them.

What to Replace?:

Unless there are unused frames, one page must be replaced for each page that is loaded into memory. A *replacement policy* specifies how to determine which page to replace.

Similar issues arise if (pure) segmentation is used, only the unit of data transfer is segments rather than pages. Since segments may vary in size, segmentation also requires a *placement policy*, which specifies where, in memory, a newly-fetched segment should be placed.

Page Faults

- When paging is used, some valid pages may be loaded into memory, and some may not be.
- To account for this, each PTE may contain a *present* bit, to indicate whether the page is or is not loaded into memory
  - $V = 1, P = 1$: page is valid and in memory (no exception occurs)
  - $V = 1, P = 0$: page is valid, but is not in memory (exception!)
  - $V = 0, P = x$: invalid page (exception!)
- If $V = 0$, or if $V = 1$ and $P = 0$, the MMU will generate an exception if a process tries to access the page. This is called a *page fault*.
- To handle a page fault, the kernel operating system must:
  - bring the missing page into memory, set $P = 1$ in the PTE
  - while the missing page is being loaded, the faultin process is *blocked*
  - return from the exception
- the processor will then retry the instrution that caused the page fault

Page Faults in OS/161

- things are a bit different in systems with software-managed TLBs, such as OS/161 on the MIPS processor
- MMUs with software-managed TLBs never check page tables, and thus do not interpret P bits in page table entries
- In an MMU with a software-managed TLB, either there is a valid translation for a page in the TLB, or there is not.
  - If there is not, the MMU generates an exception. It is up to the kernel to determine the reason for the exception. Is this:
    * an access to a valid page that is not in memory (a page fault)?
    * an access to a valid page that is in memory?
    * an access to an invalid page?
  - The kernel should ensure that a page has a translation in the TLB *only* if the page is valid and in memory. (Why?)

A Simple Replacement Policy: FIFO

- the FIFO policy: replace the page that has been in memory the longest
- a three-frame example:

Num	1	2	3	4	5	6	7	8	9	10	11	12
Refs	a	b	c	d	a	b	e	a	b	c	d	e
Frame 1	a	a	a	d	d	d	e	e	e	e	e	e
Frame 2		b	b	b	a	a	a	a	a	c	c	c
Frame 3			c	c	c	b	b	b	b	b	d	d
Fault ?	x	x	x	x	x	x	x			x	x	

Optimal Page Replacement

- There is an optimal page replacement policy for demand paging.
- The OPT policy: replace the page that will not be referenced for the longest time.

Num	1	2	3	4	5	6	7	8	9	10	11	12
Refs	a	b	c	d	a	b	e	a	b	c	d	e
Frame 1	a	a	a	a	a	a	a	a	a	c	c	c
Frame 2		b	b	b	b	b	b	b	b	b	d	d
Frame 3			c	d	d	d	e	e	e	e	e	e
Fault ?	x	x	x	x			x			x	x	

- OPT requires knowledge of the future.

Other Replacement Policies

- FIFO is simple, but it does not consider:

  Frequency of Use: how often a page has been used?

  Recency of Use: when was a page last used?

  Cleanliness: has the page been changed while it is in memory?

- The *principle of locality* suggests that usage ought to be considered in a replacement decision.

- Cleanliness may be worth considering for performance reasons.

Locality

- Locality is a property of the page reference string. In other words, it is a property of programs themselves.
- *Temporal locality* says that pages that have been used recently are likely to be used again.
- *Spatial locality* says that pages "close" to those that have been used are likely to be used next.

In practice, page reference strings exhibit strong locality. Why?

Least Recently Used (LRU) Page Replacement

- LRU is based on the principle of temporal locality: replace the page that has not been used for the longest time
- To implement LRU, it is necessary to track each page's recency of use. For example: maintain a list of in-memory pages, and move a page to the front of the list when it is used.
- Although LRU and variants have many applications, true LRU is difficult to implement in virtual memory systems. (Why?)

Least Recently Used: LRU

- the same three-frame example:

Num	1	2	3	4	5	6	7	8	9	10	11	12
Refs	a	b	c	d	a	b	e	a	b	c	d	e
Frame 1	a	a	a	d	d	d	e	e	e	c	c	c
Frame 2		b	b	b	a	a	a	a	a	a	d	d
Frame 3			c	c	c	b	b	b	b	b	b	e
Fault ?	x	x	x	x	x	x	x			x	x	x

The "Use" Bit

- A *use bit* (or *reference bit*) is a bit found in each page table entry that:
  - is set by the MMU each time the page is used, i.e., each time the MMU translates a virtual address on that page
  - can be read and cleared by the operating system
- The use bit provides a small amount of efficiently-maintainable usage information that can be exploited by a page replacement algorithm.

The Clock Replacement Algorithm

- The clock algorithm (also known as "second chance") is one of the simplest algorithms that exploits the use bit.
- Clock is identical to FIFO, except that a page is "skipped" if its use bit is set.
- The clock algorithm can be visualized as a victim pointer that cycles through the page frames. The pointer moves whenever a replacement is necessary:

```
while use bit of victim is set
   clear use bit of victim
   victim = (victim + 1) % num_frames
choose victim for replacement
victim = (victim + 1) % num_frames
```

Page Cleanliness: the "Modified" Bit

- A page is *modified* (sometimes called dirty) if it has been changed since it was loaded into memory.
- A modified page is more costly to replace than a clean page. (Why?)
- The MMU identifies modified pages by setting a *modified bit* in page table entry of a page when a process *writes* to a virtual address on that page, i.e., when the page is changed.
- The operating system can clear the modified bit when it cleans the page
- The modified bit potentially has two roles:
  - Indicates which pages need to be cleaned.
  - Can be used to influence the replacement policy.

How Much Physical Memory Does a Process Need?

- Principle of locality suggests that some portions of the process's virtual address space are more likely to be referenced than others.
- A refinement of this principle is the *working set model* of process reference behaviour.
- According to the working set model, at any given time some portion of a program's address space will be heavily used and the remainder will not be. The heavily used portion of the address space is called the *working set* of the process.
- The working set of a process may change over time.
- The *resident set* of a process is the set of pages that are located in memory.

According to the working set model, if a process's resident set includes its working set, it will rarely page fault.

Resident Set Sizes (Example)

```
PID   VSZ  RSS COMMAND
805 13940 5956 /usr/bin/gnome-session
831  2620  848 /usr/bin/ssh-agent
834  7936 5832 /usr/lib/gconf2/gconfd-2 11
838  6964 2292 gnome-smproxy
840 14720 5008 gnome-settings-daemon
848  8412 3888 sawfish
851 34980 7544 nautilus
853 19804 14208 gnome-panel
857  9656 2672 gpilotd
867  4608 1252 gnome-name-service
```

Thrashing and Load Control

- What is a good multiprogramming level?
  - If too low: resources are idle
  - If too high: too few resources per process
- A system that is spending too much time paging is said to be *thrashing*. Thrashing occurs when there are too many processes competing for the available memory.
- Thrashing can be cured by load shedding, e.g.,
  - Killing processes (not nice)
  - Suspending and *swapping out* processes (nicer)

Swapping Out Processes

- Swapping a process out means removing all of its pages from memory, or marking them so that they will be removed by the normal page replacement process. Suspending a process ensures that it is not runnable while it is swapped out.
- Which process(es) to suspend?
  - low priority processes
  - blocked processes
  - large processes (lots of space freed) or small processes (easier to reload)
- There must also be a policy for making suspended processes ready when system load has decreased.